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# OCP Accelerator Module (OAM) Design Specification v1.5

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### **3 Acknowledge**

We want to acknowledge all the OCP OAI Workstream members for their contributions to this specification: The incredible collaboration between customers, accelerator manufacturers, system developers, and industry partners shows how Open Compute develops industry-standard form factors and specifications that benefit all its members.

We would especially like to thank Google, H3C, Inspur, Intel, Meta, Molex, and Wiyynn for their extra efforts in putting this specification together.

## 4 Overview

Artificial Intelligence (AI) applications are rapidly evolving and producing an explosion of new types of hardware accelerators for Machine Learning (ML), Deep Learning (DL), and High-performance Computing (HPC).

Different implementations target similar requirements for power/cooling, robustness, serviceability, configuration, programming, management, debug, inter-module communication to scale-up, and input/output bandwidth to scale out.

To take advantage of the available industry-standard form factors to reduce the required time and effort in producing suitable solutions, various implementations have selected the PCIe CEM form factor as a quick market entry.

Such solutions are not optimized for the upcoming AI workloads, which require ever-growing bandwidth and interconnect flexibility for data/model parallelism.

The state-of-the-art applications require multiple cards in a system with various inter-card links running at high-speed interconnect bandwidth between cards.

Using the PCIe CEM form factor to meet such interconnect requirements poses several challenges. These include excessive signal insertion loss from ASIC to PCIe connectors and baseboard, inter-card cabling complexity reducing robustness and serviceability, and limits the supported inter-ASIC topologies.

This base specification outlines an interoperable, modular hierarchy based on the OAM form factor (OCP Accelerator Module), an interconnect Baseboard, a Tray, and a Chassis. It enables flexible high-speed interconnect topologies for multi-ASIC solutions,

- OAM (various accelerators)
- Baseboard (interconnecting topologies between accelerators, hosts, and other IO devices to scale up)
- Tray (a means for ease of field replacement and serviceability)
- Chassis (an outline for a collection of Trays and input/output resources to scale out)

Based on this base specification, various design and product implementations may maintain interoperability while offering enhancements in each hierarchy level.

We invite open contributions in the following areas:

1. Base specification (OCP Accelerator Infrastructure Project Specification)
2. Design specification (This document, detailed description of alternative, interoperable components which meet the base specification)
3. Products (schematic, layout, mechanical/thermal solutions, and firmware/software to realize the above designs)

## 4.1 Scope

The OAM design specification defines the form factor, standard specifications for a compute accelerator module, and a compliant baseboard design enabling interoperability across multiple ASIC or GPU-based mezzanine modules and baseboard design interfaces.

The OAM form factor facilitates scalability across accelerators by simplifying the system solution when interconnecting communication links among modules compared to a PCIe Add-in card form factor.

## 4.2 Acronyms

Acronym	Definition
ASIC	Application Specific Integrated Circuit
OAM	OCP Accelerator Module
BGA	Ball Grid Array
BMC	Baseboard Management Controller
TDP	Thermal Design Power
EDP	Excursion Design Power
GPU	Graphic Processing Unit
MPN	Manufacturing Part Number
DXF	Drawing eXchange Format
PCBA	Printed Circuit Board Assembly



## 5 High-Level Specification for the OCP Acceleration Module

Module Dimension	102mm x 165mm
Board Thickness	1.57 - 3.20mm $\pm$ 10%
Module Power/Input Voltage	<ul style="list-style-type: none"><li>○ High power module supports up to 700W, using 44V-59.5V DC as input power</li><li>○ Low power module supports up to 350W, using 11-13.2V DC as input power</li></ul>
Connectors	2* Molex Mirror Mezz Pro Connectors (MPN: 218910-1115)  Stack height 5mm  Differential pair Impedance: 90ohm $\pm$ 5%
Host Interface	One or two x16 host links. E.g., PCIe Gen3/4/5 x16, or alternate protocols.
Module to Module Interconnect Links	Up to 7 Links per module, each link has up to X16-X20 lanes  Each link may be able to be configured into sub-links.
Bottom stiffener height (including Mylar)	5 $\pm$ 0.15mm

## 6 OAM Mechanical Specifications

This section describes the OAM form factor. It uses a single accelerator ASIC on the module as an example to illustrate the mechanical specifications. The top and bottom stiffeners may be different if the modules have multiple accelerator ASICs.

Please refer to 2D DXF and 3D files for further details. 2D DXF and 3D files are in the contribution package, with relevant reference drawings to mechanical components. Please note that some OAM features call out as required, but others include them for reference.

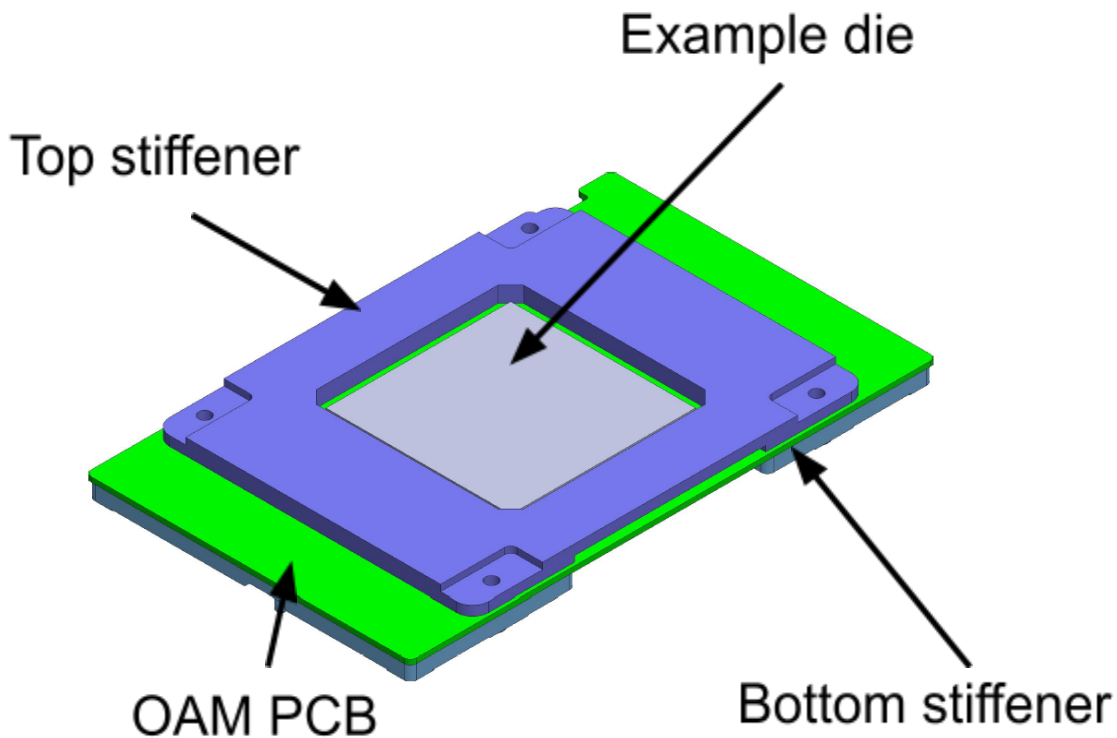


Figure 1 OAM isometric view

### 6.1 Module PCBA Form Factor

This section covers the required and recommended dimensions of the module PCBA and its parts. Figures 2 and 3 illustrate the OAM form factor and dimensions, with all the measurements in Figure 2 required. It is a 102mm x 165mm PCB size, Mezzanine Connectors on the bottom side, and the accelerator on the top side. The connector to connector pitch is 102mm. Four NPTH mounting holes attach the module to a corresponding bolster plate secured below the system PCB. These mounting holes should provide clearance for an M3.5 screw with enough thread length to secure the bottom stiffener. There is a notch located near the southwest corner of the board, adjacent to Connector 1. For connector orientation, see Figure 4 - Top and bottom views of the OAM Assembly.

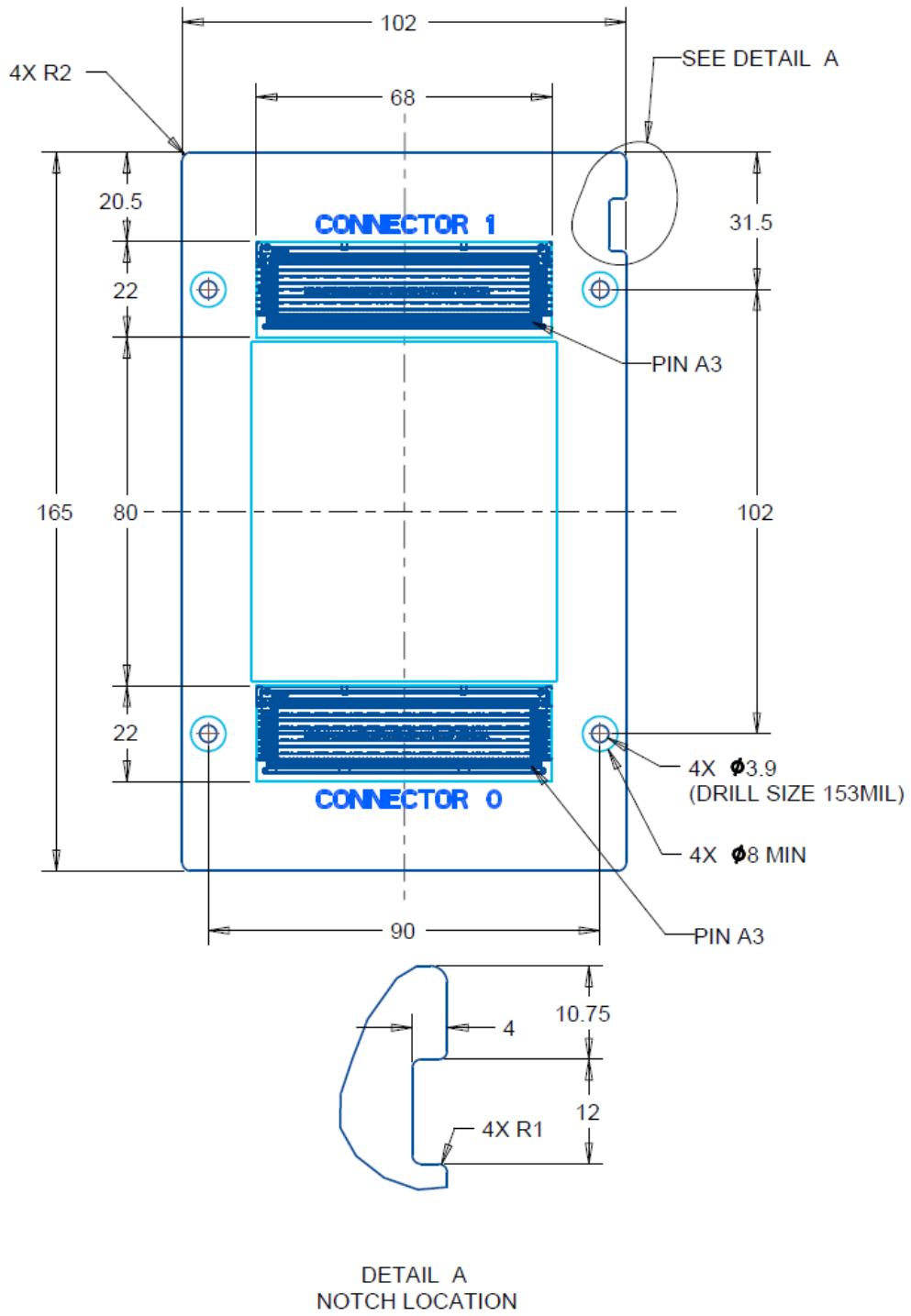


Figure 2 102mm wide OAM Form Factor Dimensions, Bottom View



Figure 3 OAM Form Factor, Side View with System Baseboard

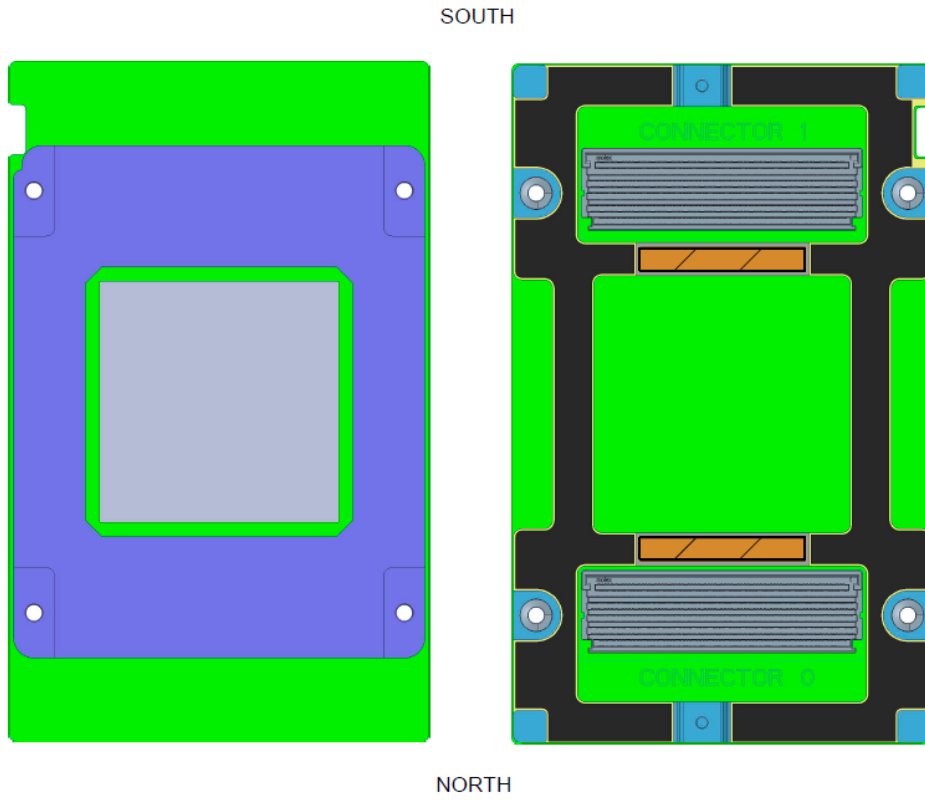


Figure 4 Top and bottom views of the OAM Assembly

## 6.2 Mezzanine Connector

Molex Mirror Mezz Pro (MPN: 218910-1115) is the PCB to PCB interconnect solution supported by the OAM form factor. Mirror Mezz Pro is a highspeed differential pair-based mezzanine connector in a footprint-identical genderless plug and receptacle part for module and baseboard. Figure 5 Mirror Mezz Pro 209311-7001 is provided courtesy of Molex.

- Stack height: 5mm
- Mating Force: 0.50N/pin Max, total 344.0N MAX. Data on mate forces of the 218910-1115 connector is in Table 1 Mate/Unmate Averaged Data for Molex Mirror Mezz Pro 218910-1115.
- Unmating force: 0.045N/pin MIN, total 31.0N MIN. Data on the unmate force of the 218910-1115 connector is in Table 1 Mate/Unmate Averaged Data for Molex Mirror Mezz Pro 218910-1115.
- Weight of OAM + Heatsink: 2kg MAX
- 172 Total Differential Pairs, of which 161 are fully ground shielded (non-orphan)

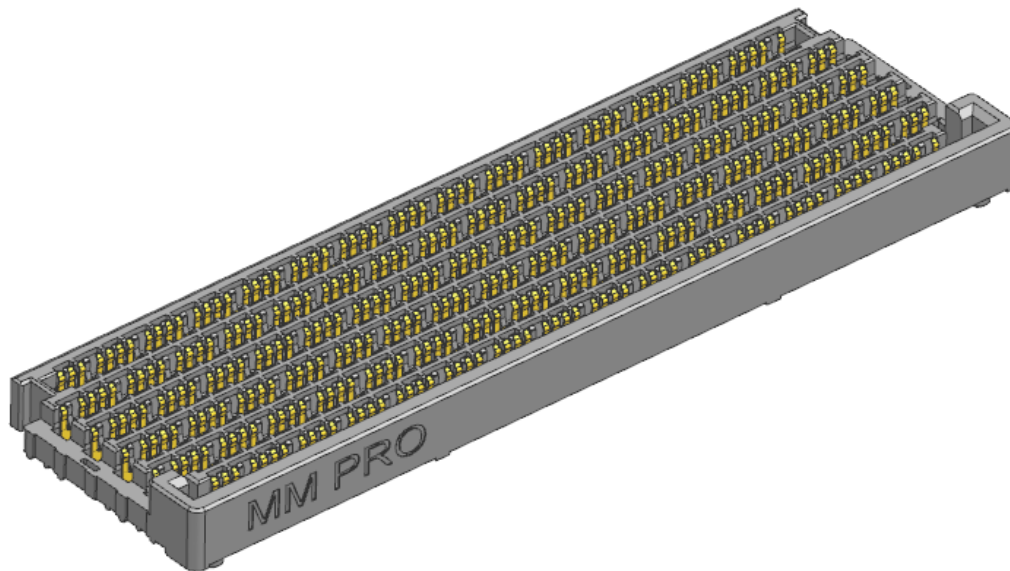


Figure 5 Mirror Mezz Pro 218910-1115

## 6.2.1 Mate/Unmate Force Data

The mating connectors will be vertically inverted when mated.

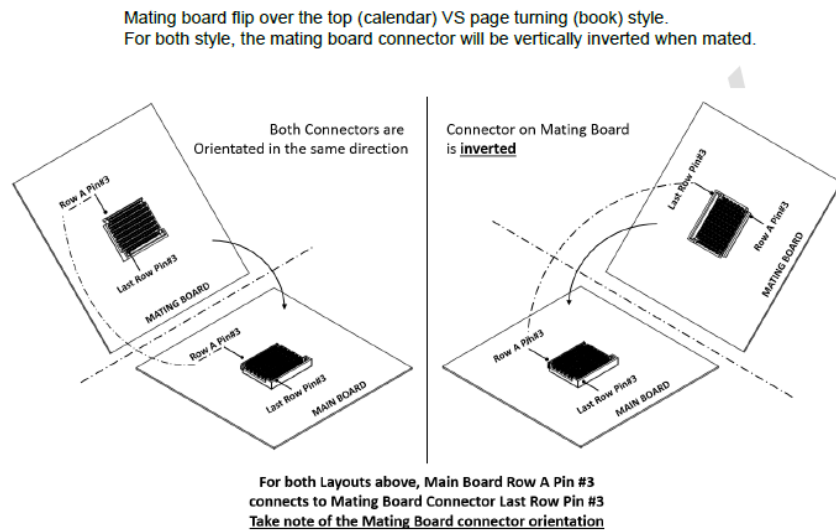


Figure 6 Mirror Mezz Pro Connector Mating

The mate and unmate forces provided in the product specification are conservative. The specific 218910-1115 connector that the OAM uses has mate/unmate forces more in line with those found in Table 1 Mate/Unmate Averaged Data for Molex Mirror Mezz Pro 218910-1115 and in Figure 7 Measured Mate Force per Pin for Molex Mirror Mezz Pro 218910-1115. The mating force per pin trends upwards for the initial 5 cycles before settling back towards the average of 0.41N/pin.

Table 1 Mate/Unmate Averaged Data for Molex Mirror Mezz Pro 218910-1115

Mate and Un-mate Force (unit:N)

Unit:N	Cycle	1st	2nd	3rd	4th	5th	Max	Min	Ave
Mating Force	Sample1	267.5	279.4	292.8	300.4	309.5	309.5	250.9	280.7
	Sample2	253.5	263.1	278.6	286.9	298.5			
	Sample3	263.4	268.5	286.5	290.3	303.0			
	Sample4	266.1	275.7	292.6	294.4	294.9			
	Sample5	264.0	277.6	290.3	294.9	299.5			
	Sample6	260.2	262.8	279.5	277.4	277.9			
	Sample7	250.9	263.1	270.2	279.5	282.3			
	Sample8	263.2	264.4	273.5	287.7	289.5			
	Sample9	261.4	268.1	285.4	289.8	293.4			
	Sample10	274.0	285.5	294.5	300.8	306.4			
Un-mating Force	Sample1	151.0	161.5	173.6	184.5	185.4	185.6	151.0	176.1
	Sample2	162.8	176.3	181.1	181.4	180.9			
	Sample3	162.7	179.1	182.5	184.8	185.6			
	Sample4	159.7	176.6	182.1	182.6	184.9			
	Sample5	169.0	179.4	184.0	184.7	183.9			
	Sample6	159.8	170.1	172.5	173.6	176.3			
	Sample7	160.0	173.1	176.6	178.1	178.6			
	Sample8	161.8	177.0	177.3	180.5	181.6			
	Sample9	162.1	175.2	179.4	181.1	181.8			
	Sample10	168.3	182.3	185.3	185.3	184.8			

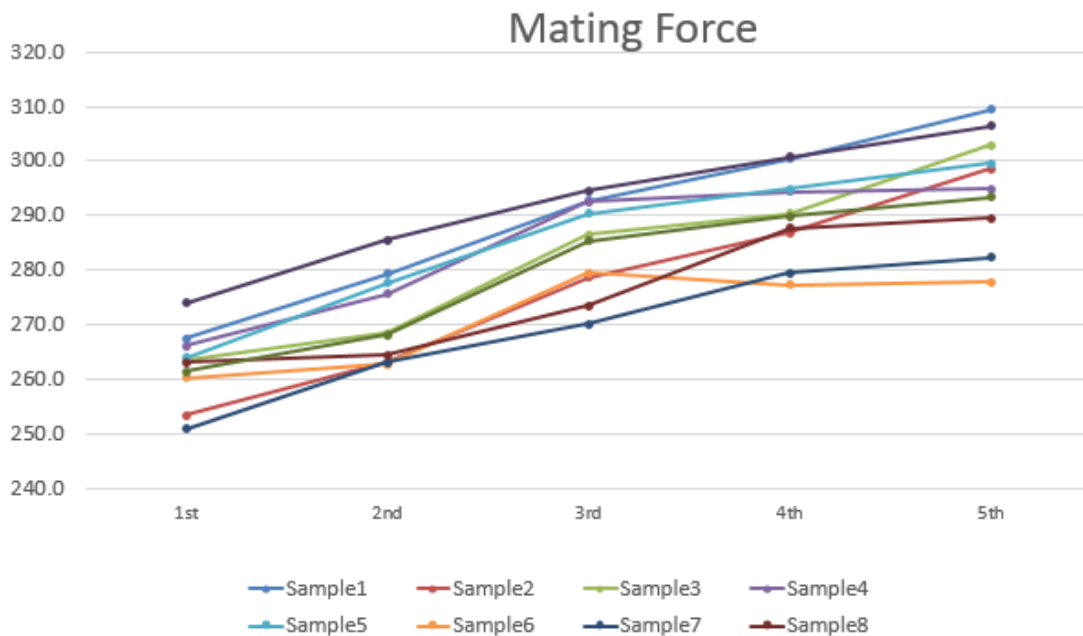


Figure 7 Measured Mate Force per Pin for Molex Mirror Mezz Pro 218910-1115

### 6.3 OAM Top Stiffener

The reference model for the OAM top stiffener is purely referenced, and dimensions may be changed or adjusted to accommodate the specific application and board layout of the OAM PCB.

### 6.4 OAM Bottom Stiffener

The reference model for the OAM bottom stiffener is in Figure 8 Reference Design of Bottom Stiffener. Required dimensions are in Figure 9 Bottom Stiffener Required Dimensions. The bottom stiffener must accommodate the SMT nuts of sizes shown in Figure 15 SMT Receiving Nut for Baseboard. Other features and dimensions of the bottom stiffener shown in the reference model are optional and can be adjusted based on the needs of the module PCB.

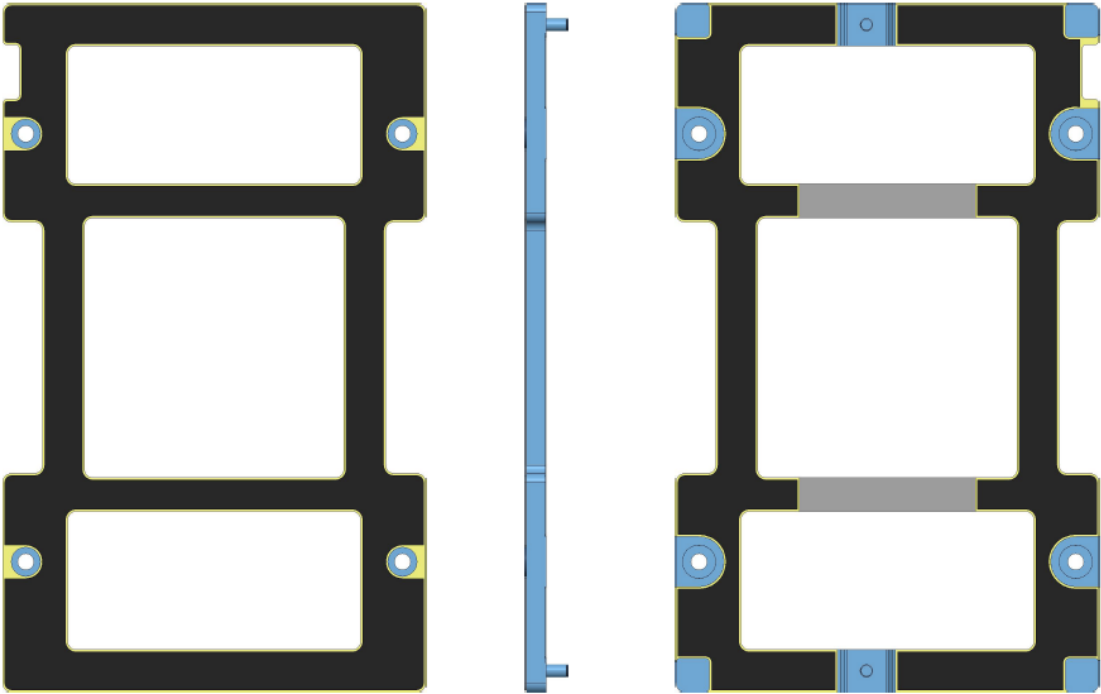
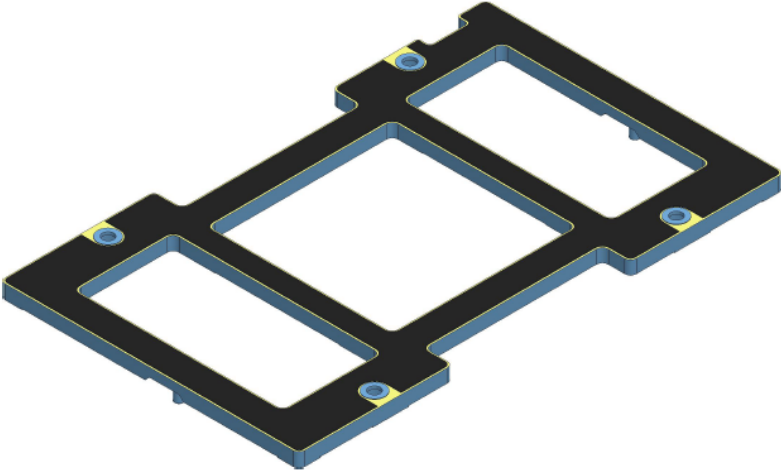




Figure 8 Reference Design of Bottom Stiffener

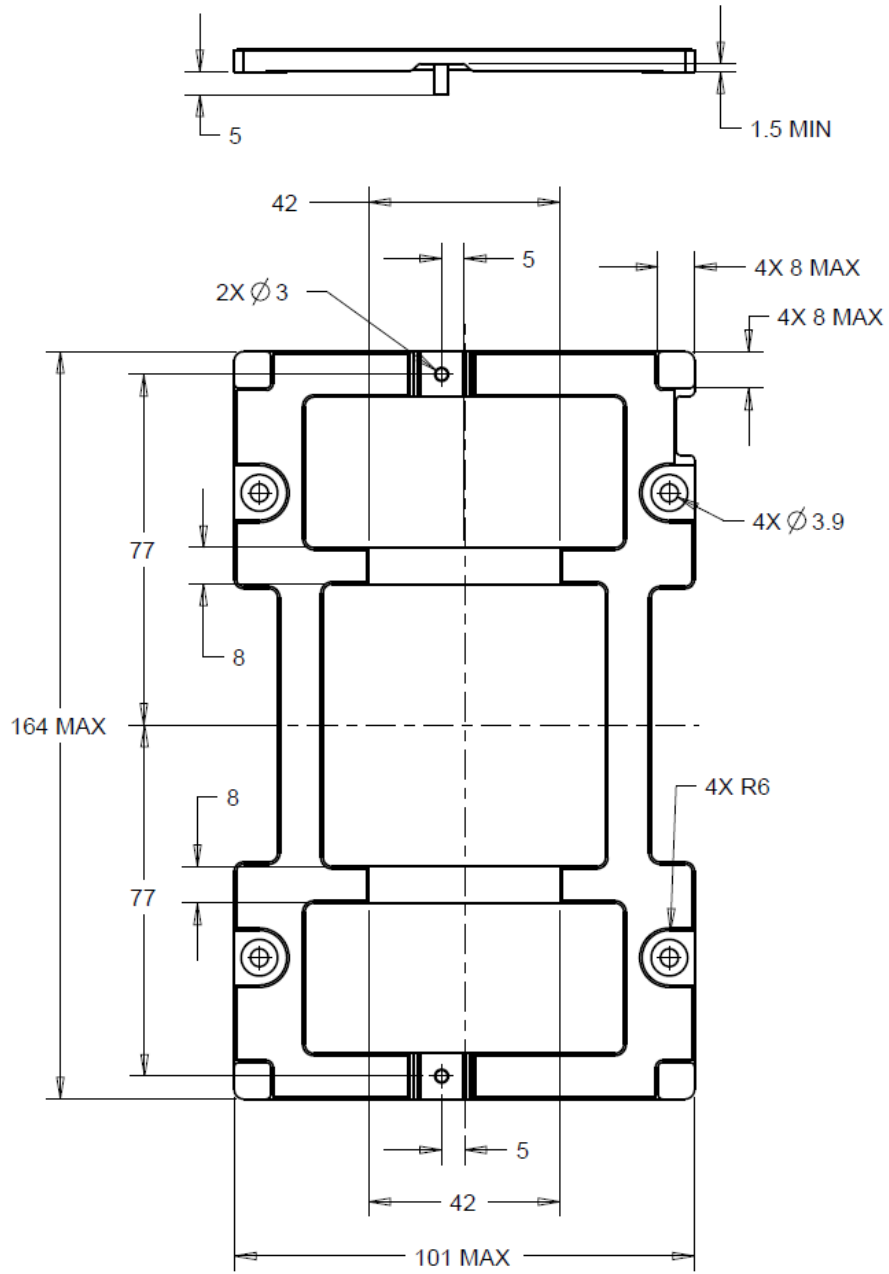


Figure 9 Bottom Stiffener Required Dimensions

### 6.4.1 Tolerance Stack-up of Bottom Stiffener

Standoff height as recommended by Molex for the Mirror Mezz Pro Connector is  $5\text{mm} \pm 0.15\text{mm}$ . This tolerance may be difficult to attain using an insulator-adhesive-stiffener-adhesive-insulator stack, so it is highly recommended that pockets be machined into the stiffener to account for the tolerances of the insulator and adhesive (see reference design CAD for further details). With a stiffener only stack, 0.15mm should be easily attainable.

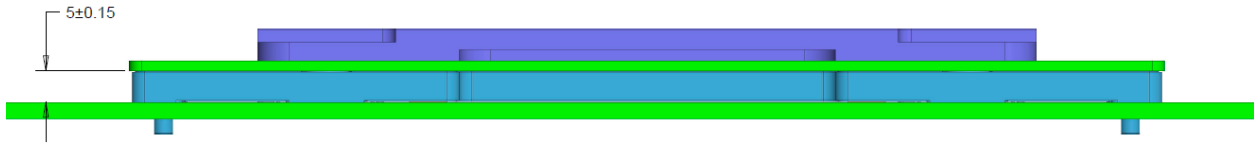


Figure 10 Tolerance Stack-up of Bottom Stiffener

### 6.4.2 Alignment Pins

There are two alignment pins required on the bottom stiffener of the OAM, intended as guidance features and an additional keying feature for the module (see Section 6.5 for more details). The pins are 3mm diameter, with a length of 10mm measured from the bottom of the OAM PCB. Note that since there may be components on the bottom side of the PCB, if the stiffener pocket in this area, the total length of the pin will be shorter than 10mm. The minimum thickness of the stiffener is 1mm in these areas, as recommended. Figure 12 shows an example of a possible alignment pin. Note that the length will vary depending on the specifically chosen geometry of the bottom stiffener.

MPN: PEM TPS-3mm-8 or equivalent

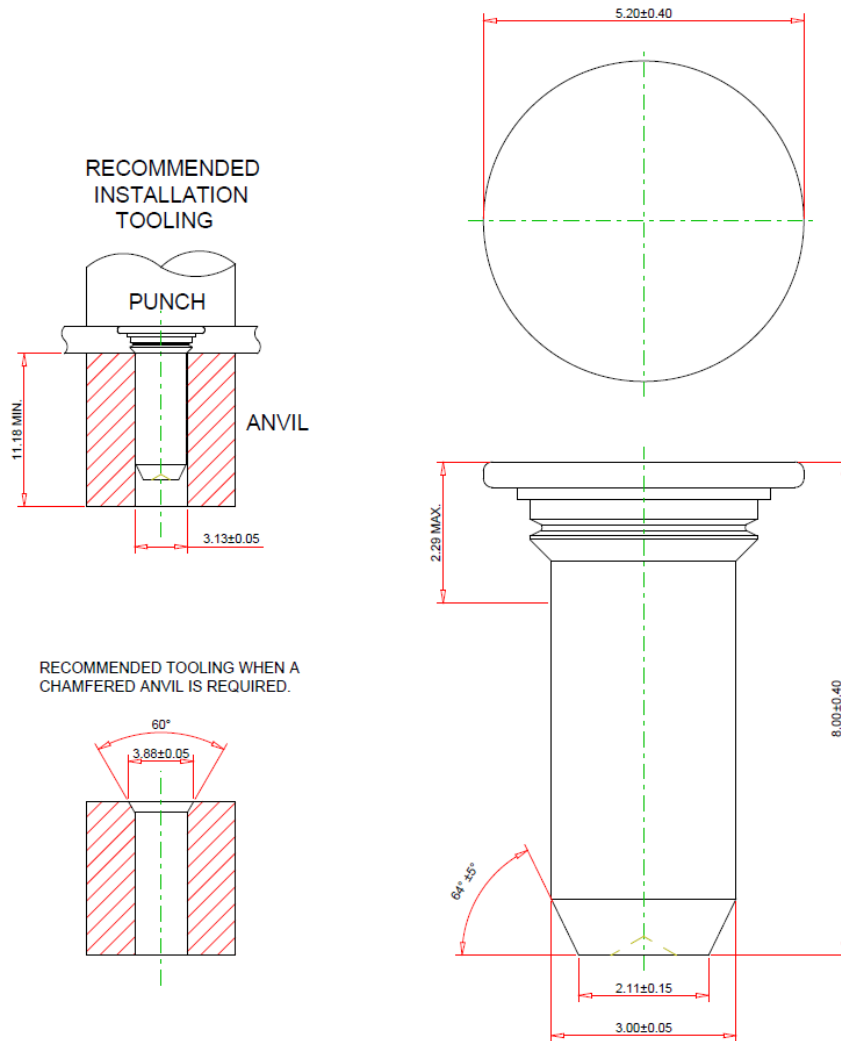


Figure 11 Alignment pin example

### 6.4.3 EMI Gaskets / Pads

The bottom stiffener has two defined areas of 8x42mm size, reserved for the placement of fabric-over-foam gaskets. This area designs to have a 0.5mm depth, and the gasket defined should have a 6x40mm footprint, with a 1mm height. It provides a 50% nominal compression and solid grounding to the baseboard (equivalently designed ground pad).

MPN: Laird 4Y03PC51H00158 or equivalent

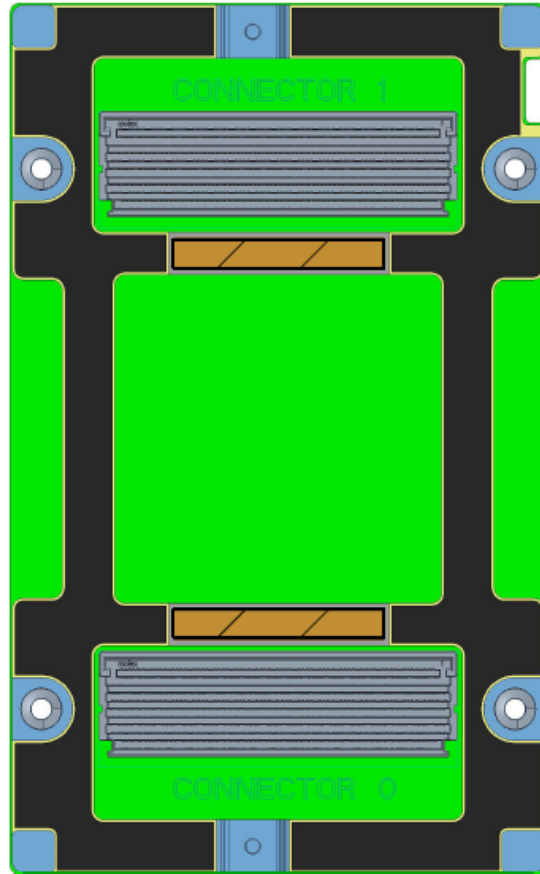


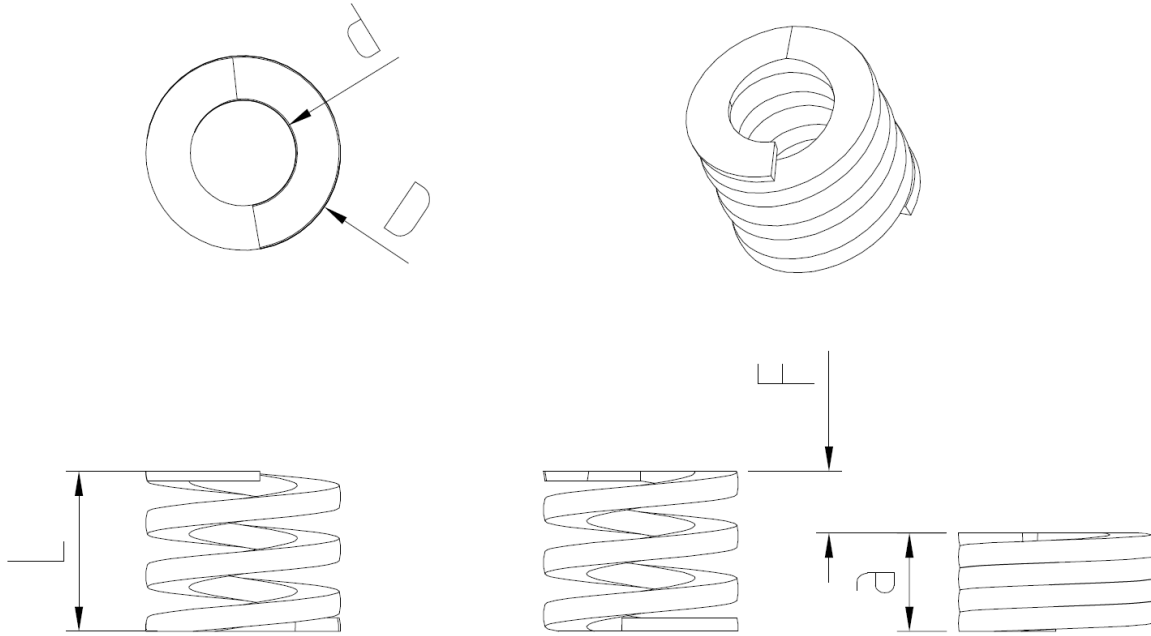
Figure 12 Fabric-over-foam Gasket Locations (brown)

#### 6.4.4 Die Springs

Due to many pins, the mate and unmate forces of the Molex Mirror Mezz Pro connectors are high (see Section 6.2.1). Die springs are to be used to assist with the de-mate. It is strongly suggested for OAM vendors to use this reference spring in

However, an equivalent spring shall have a spring constant of at least 70N/mm and at least 2.5mm compression. The inner diameter shall be 4.2mm, and the outer diameter shall be 7.8mm. These springs fit into 8mm diameter counterbores of 4mm depth in the bottom stiffener. The installation method uses glue (3M DP810 or equivalent), applied with a maximum thickness of 0.1mm.

MPN: Timson WG774265 or equivalent



D (mm)	d (mm)	L (mm)	a (mm)	F (mm)	K (N/mm)
7.8 <sup>+0.05</sup> <sub>-0.20</sub>	4.2 <sup>+0.1</sup> <sub>-0.15</sub>	6.5 <sup>+0.2</sup> <sub>-0.2</sub>	3.6 <sup>+0.15</sup> <sub>-0.15</sub>	2.9 <sup>+0.35</sup> <sub>-0.35</sub>	78.6±10%

Figure 13 Die Spring dimensions and drawing

Table 2 Spring constant and free length of die springs, shown compared to cycle count

	Sample 1		Sample 2		Sample 3		Sample 4		Sample 5	
	L (mm)	K (N/mm)	L (mm)	K (N/mm)	L (mm)	K (N/mm)	L (mm)	K (N/mm)	L (mm)	K (N/mm)
1	6.48	81.87	6.44	80.88	6.48	82.12	6.45	80.20	6.46	80.70
2	6.47	81.23	6.43	79.80	6.47	81.86	6.44	79.98	6.46	80.58
3	6.47	81.01	6.42	79.84	6.47	81.33	6.44	79.96	6.45	80.48
4	6.46	80.95	6.42	79.70	6.46	81.20	6.44	79.80	6.45	80.46
5	6.46	80.95	6.41	79.37	6.46	81.17	6.43	79.68	6.44	80.28
6	6.46	80.90	6.41	79.22	6.46	81.13	6.43	79.40	6.44	80.29
7	6.46	80.79	6.40	79.31	6.45	80.97	6.42	79.52	6.43	80.12
8	6.45	80.77	6.40	79.16	6.45	81.17	6.42	79.48	6.43	80.02
9	6.45	80.76	6.39	79.11	6.43	80.98	6.41	79.47	6.42	79.90
10	6.44	80.68	6.39	79.02	6.43	80.91	6.41	79.38	6.42	79.93
<b>Avg</b>	<b>6.46</b>	<b>80.99</b>	<b>6.41</b>	<b>79.54</b>	<b>6.46</b>	<b>81.28</b>	<b>6.43</b>	<b>79.69</b>	<b>6.44</b>	<b>80.28</b>

## 6.5 Baseboard Keep out Zone & Grounding Pads

The below figure shows the baseboard outline (top side view) required to accommodate this module. All cross-hatched areas are needed to be grounded except for the four corners 10x10 square holes. The 10x10 square holes in the corners are highly recommended for being grounded. Additionally, it is recommended to route high-speed traces away from mounting hole areas due to large compression forces from the die spring.

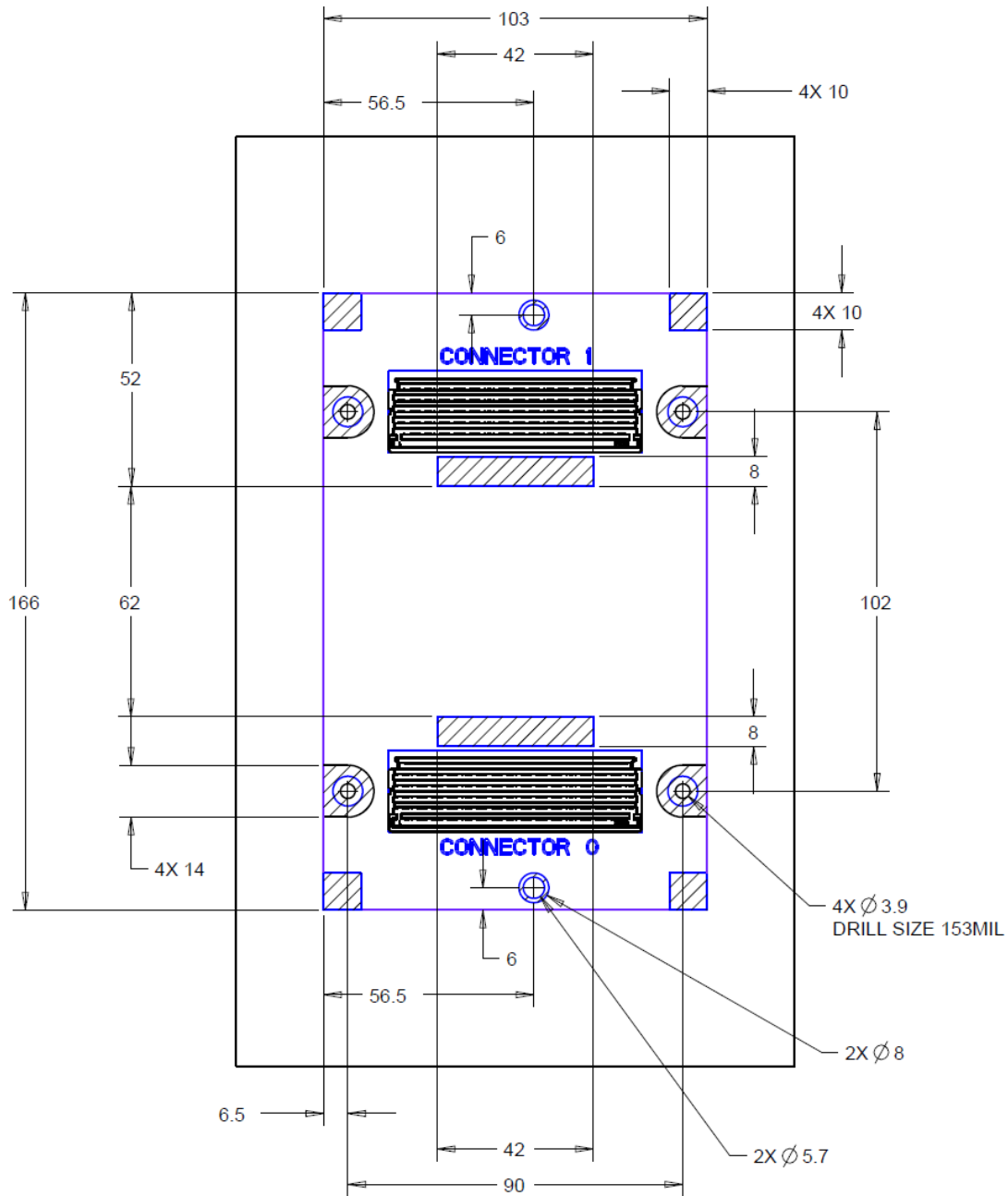


Figure 14 Baseboard KOZ and Grounding Pad Dimensions

### 6.5.1 SMT Nut

Two SMT nuts with the dimensions shown in Figure 17 are to be soldered to the baseboard in the locations with 5.7mm diameter holes. These nuts provide the mating features to the alignment pins on the bottom stiffener of the OAM. Clearance of the 3mm pins in the 3.6mm nuts means that the module will come within 0.3mm of its final position.

MPN: Ray Home 1000401319 or equivalent

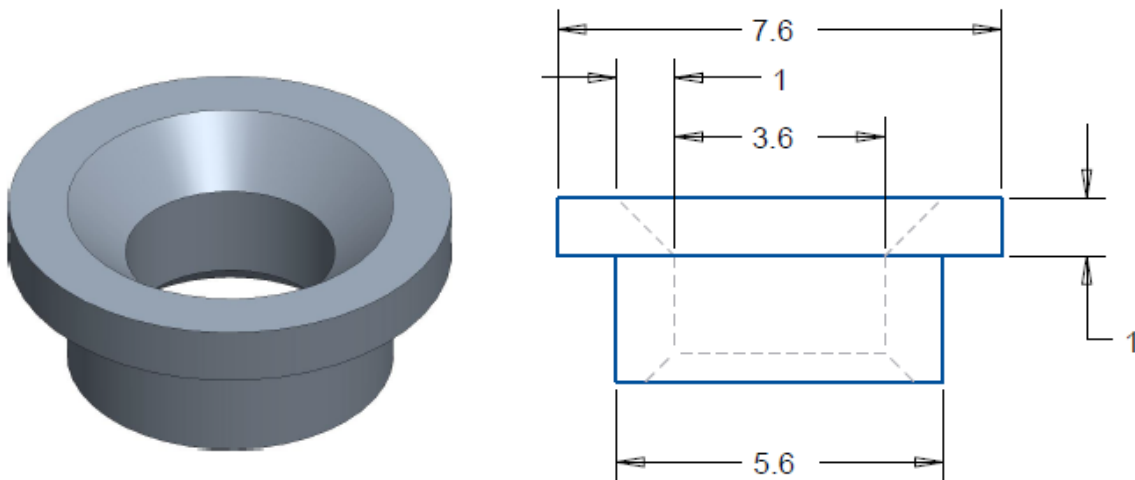


Figure 15 SMT Receiving Nut for Baseboard

### 6.5.2 Component Keep-out Zone

The baseboard has a component keep-out zone of 103x166mm, as shown in Figure 14 Baseboard KOZ and Grounding Pad Dimensions.

### 6.5.3 Grounding Pads

As with the bottom stiffener, the baseboard has two grounding pads of size 8x42mm, for the EMI fabric-over-foam gaskets on the stiffener to provide good contact. Refer to Section 4.3.3 for gasket MPN and description.

## 6.6 Recommended Alignment Features

There are three stages of engagement when installing the OAM to the system.

Stage 1: Notch in top of heatsink providing visual guidance and orientation reference. The reference design shows 1mm clearances (plastic top is 103mm with a 0.5mm bumper on each side of the module).

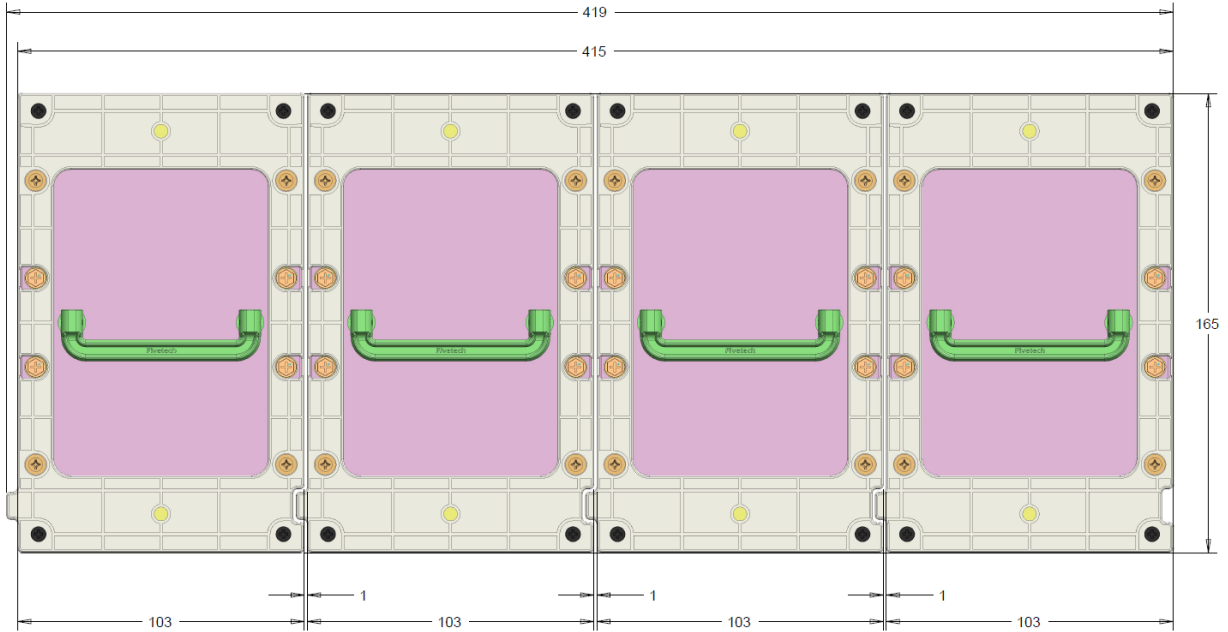


Figure 16 Top view of four adjacent OAM with heatsinks

Stage 2: Alignment pins, two 3mm pins from the OAM into two 3.6mm SMT nuts on the baseboard.



Figure 17 Side view (exploded) showing alignment pins being received by 1mm tall SMT nuts

Stage 3: Connector housing built-in engagement (Molex Mirror Mezz Pro gather ability: 0.76mm).



Figure 18 Side view (exploded) showing mezzanine connectors doing final alignment



## 6.7 Reference Heatsink Design

An air-cooled solution recommends TDP equal to or less than 450W modules. For modules that are over 450W, consider other solutions such as liquid cooling.

The below figure shows the reference model of the heatsink with OAM assembly.

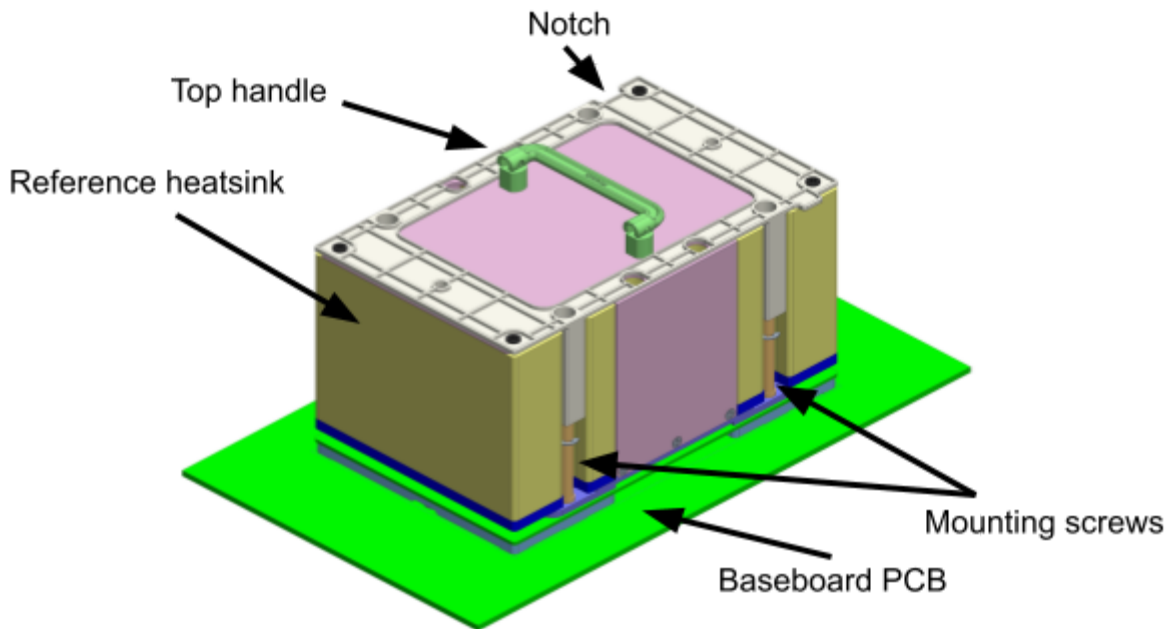


Figure 19 Reference Model of Heatsink with OAM Assembly

### 6.7.1 Top Handle

Due to the size and bulk of the heatsink and module assembly, a handle is recommended. The reference design uses a folding handle. This handle screws into a sheet metal panel attached to the heat sink base with six M2.5 flathead screws. This attachment method allows the load to transfer through the more rugged base instead of the delicate heat sink fins.

MPN: Fivetech 62-57P-064-7-02-5 or equivalent

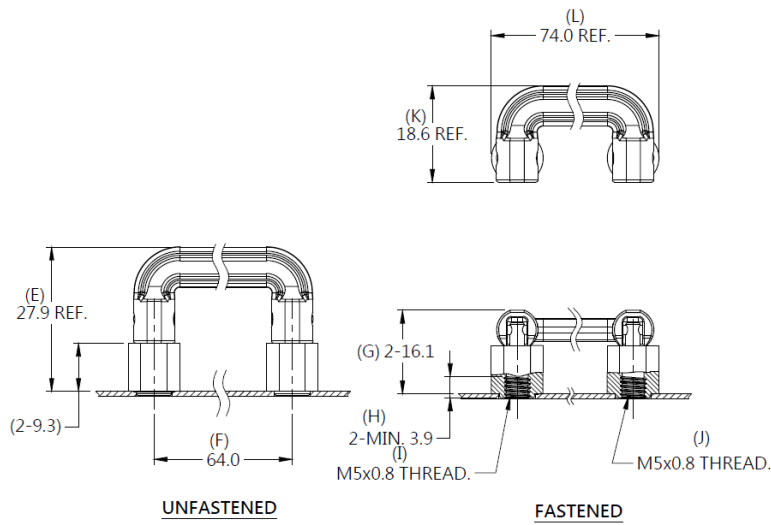


Figure 20 Dimensioned Smart Folding Handle from Reference Design

### 6.7.2 Long Screw Attachment

A set of four M3.5, spring-loaded, Phillips head long screws are used to attach the module to the baseboard. Note that the reference screw provided is simply a reference and that L3 and L4 will need to be adjusted based on the thicknesses of the baseboard and bolster plates. However, these mounting screw locations are fixed per the requirements of the OAM board layout and the baseboard layout. Each screw clears the top stiffener, mezzanine PCB, bottom stiffener (including the die spring), and the baseboard to screw directly into the bolster plate below the baseboard PCB. It is recommended that the OAM be attached to the baseboard by torquing the screws in a diagonal pattern.

MPN of Long Screw: Wujiang Screw MDCM0359733N or similar

MPN of Spring for Long Screw: Surpassing Hardware Spring FDJG7004010 or similar

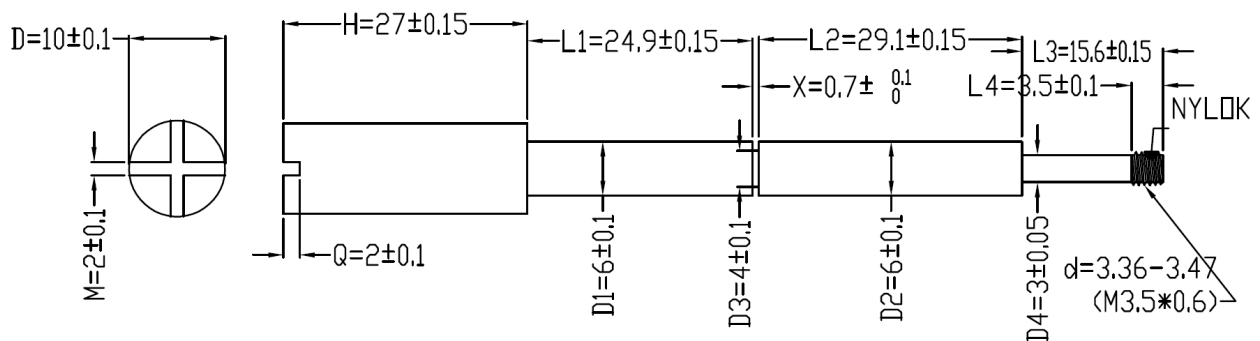


Figure 21 Drawing of Wujiang Screw MDCM0359733N

## 7 Thermal Specification

### 7.1 Environmental Conditions

The thermal and cooling solution should dissipate heat from the components when the module operates at its thermal design power to meet the thermal reliability requirement. The module should be able to work in the following environmental conditions without any throttling or thermal issues:

- Ambient temperature: 5°C to 35 °C
- Approach temperature: 10°C to 48 °C, considering shadowing other components
- Altitude: sea level to 3000 ft\*, without temperature duration
- Relative Humidity: 20% to 90%
- Cold boot temperature: the module should be able to boot and operate at an initial temperature of 10°C

\*An extended altitude range of up to 6000ft is recommended.

In addition, the module should remain unaffected at a non-operational storage temperature range of -20°C to 85°C.

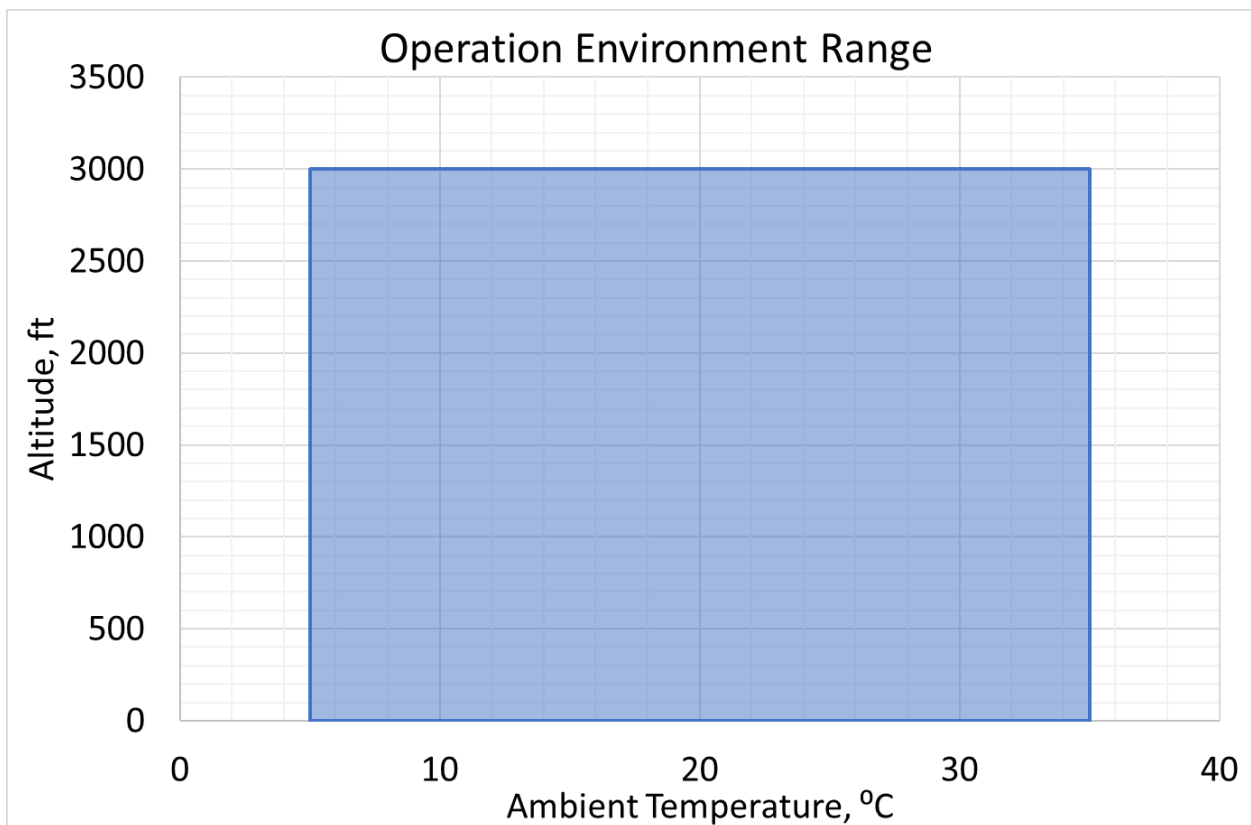


Figure 22 Module Operation Ambient Temperature

## 7.2 Temperature Report

### 7.2.1 Temperature Sensors

The module reports readings of ASIC temperature sensor and HBM temperature sensor to support software or hardware throttling, shutdown, and drive fan speed through BMC. The sensors should be located or calibrated to:

- Always report the hottest junction temperature in the component
- Keep accuracy within  $\pm 3^{\circ}\text{C}$

Lower temperature limit, non-critical temperature limit, and critical temperature limit should be defined for those temperature sensors to support throttling or shutdown features.

### 7.2.2 Remaining Components

For the remaining components that are not monitored by temperature sensors or not included in fan speed control (FSC), their cooling solutions should be appropriately designed such that:

- Before ASIC or Memory temperature readings reach throttling thresholds, they will be maintained below the temperature limits.
- When any ASIC or Memory temperature reading reaches a throttling threshold but not the hardware shutdown limit, these components will remain functional to support the reduced functionality of the module.

## 7.3 Thermal module information

To enable the module with appropriate cooling solutions, the supplier will provide the following thermal info for each product model:

- ASIC & Memory (HBM or DRAM) junction temperature limit
- ASIC & Memory (HBM or DRAM) junction to surface/case temperature correlations
- Connector surface temperature limit
- ASIC & Memory (HBM or DRAM) junction temperature range at nominal operation conditions

## 7.4 Heatsink Assembly

The module will meet these requirements to minimize the complexity of assembly, servicing, and risk of failure:

- Only one replaceable heatsink assembly (primary heatsink) is needed for the module, which can be swapped in the field.
- The other heatsink parts (i.e., secondary heatsinks) and thermal interface materials will come with the module and do not need replacement over the module lifetime.

Reliability test reports will be provided to validate the lifetime of the thermal interface materials. Shock and Vibration test reports will be provided to validate the robustness of the module assembly.

## 7.5 Thermal Recommendation

### 7.5.1 Airflow Budget

Considering OAM module meets the limits on the air delivery/removal capabilities of typical infrastructures, it is recommended that the OAM module operates with a complete performance at or below an airflow/power ratio of 0.145 CFM/W, with ambient temperature up to 30°C at sea level, equivalent to an inlet/outlet air temperature increase of 22°F.

- For operation at altitude, the same air temperature difference of 22°F is recommended.
- For a single OAM that is shadowed by other components, the airflow/power ratio calculate with airflow through its heatsink and the module power
- For an OAM shadowing other components or multiple OAMs in serial, this calculation uses the airflow through the flow channel and the sum of the power of OAM modules and upstream components.
- For OAM modules with a power lower than 300W, an airflow/power ratio of 0.1 CFM/W or lower is usually achievable and recommended.

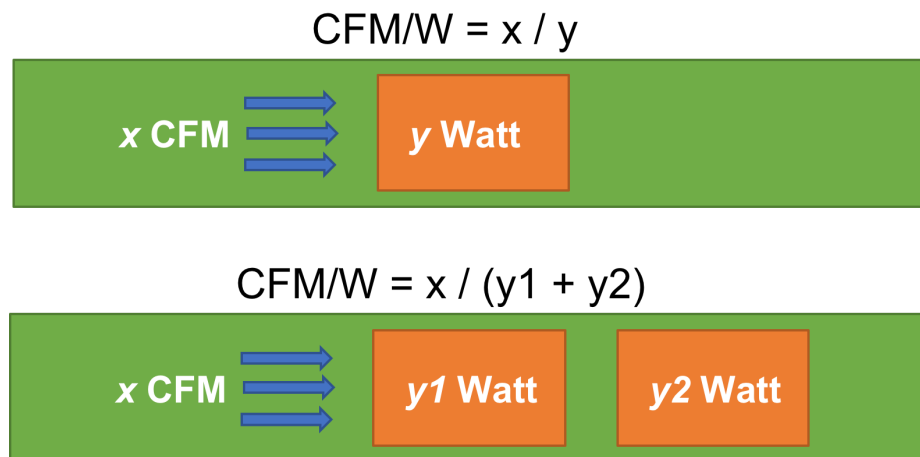


Figure 23 CFM per Watt

### 7.5.2 Reference Heatsink Design

Please refer to Figure 19 Reference Model of Heatsink with OAM Assembly. A reference heatsink design will provide to help the enablement of each product, including

- Thermal simulation model
- 3D mechanical drawing

Performance of the reference heatsink is provided in Figure 23, the thermal resistance of which calculate based on:

$$R_{ca} = \frac{T_{case} - T_{LA}}{P_{die}}$$

Where  $T_{case}$  is the surface center temp of the heater,  $T_{LA}$  is the approaching temperature, and  $P_{die}$  is the heater's power, indicating the die instead of the total module power.

Die size and power density plays an essential role in the thermal performance of the OAM module. As general guidance, this chart provides curves of three different die sizes(heater). Each product can make a preliminary estimation by referring to the curve with the closest size.

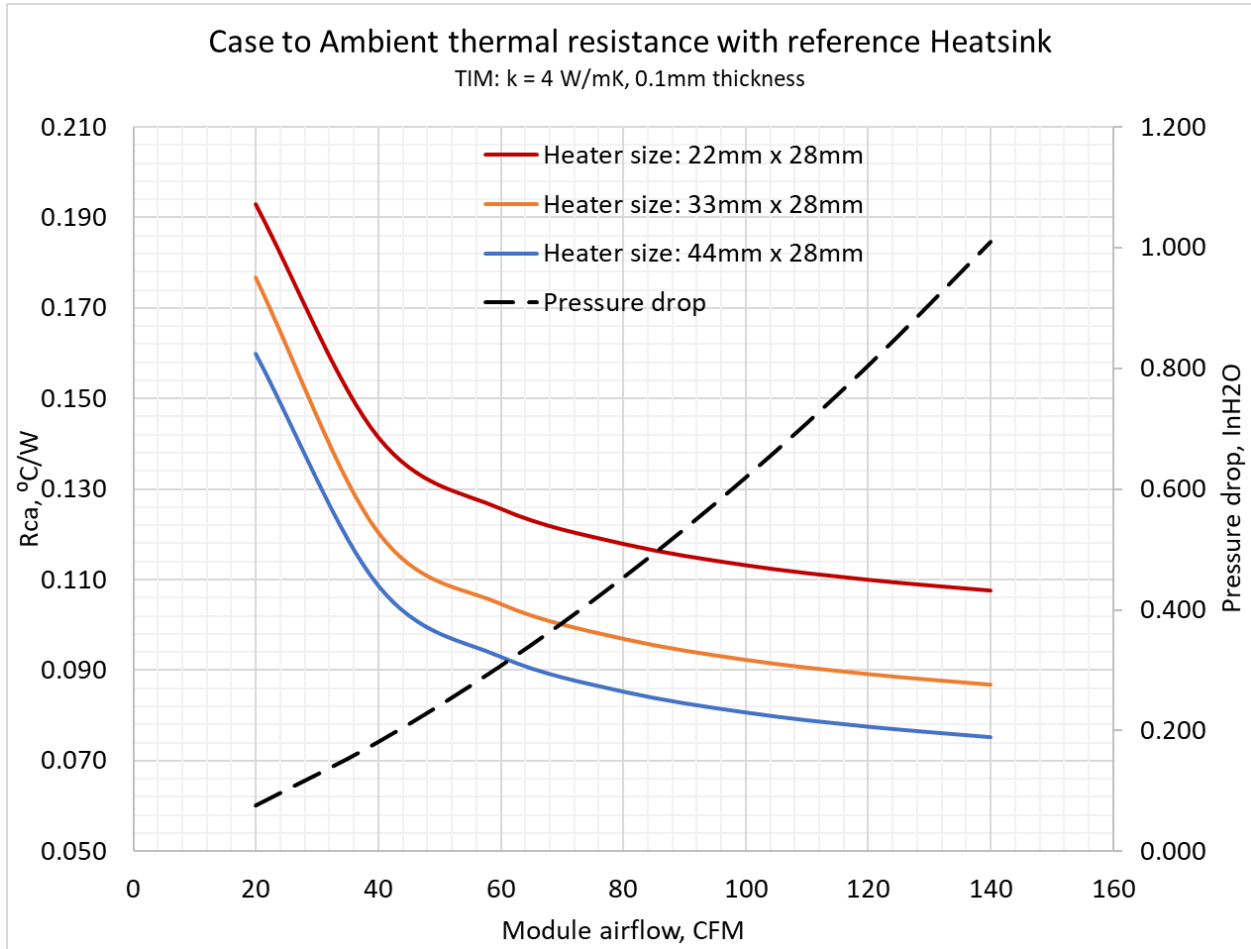


Figure 24 Thermal resistance and pressure drop of reference heatsink

If applicable, implementing a vapor chamber to spread heat in the base can achieve significant improvement. The performance of Reference heatsink design V2 with vapor chamber base is as follows:

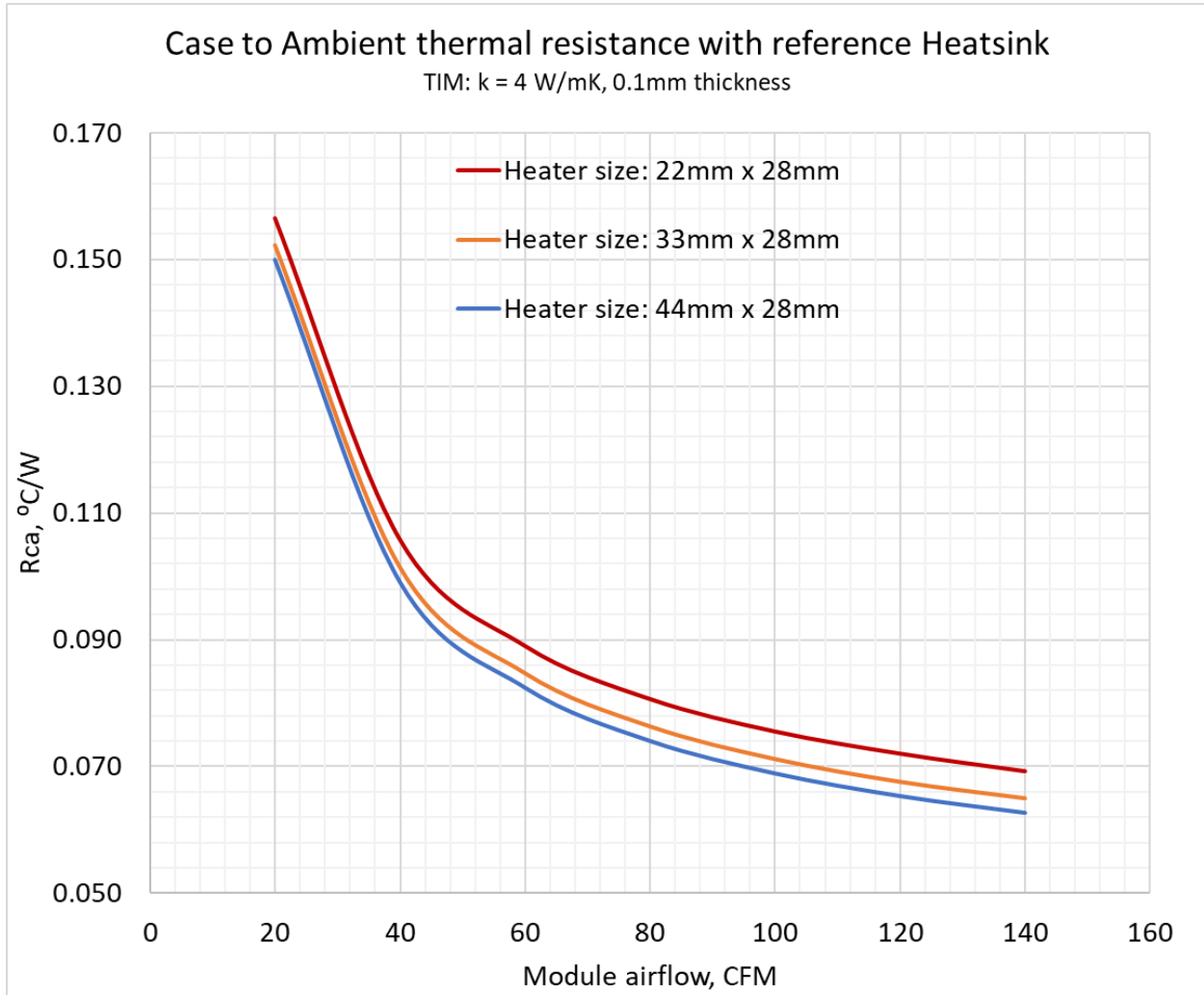
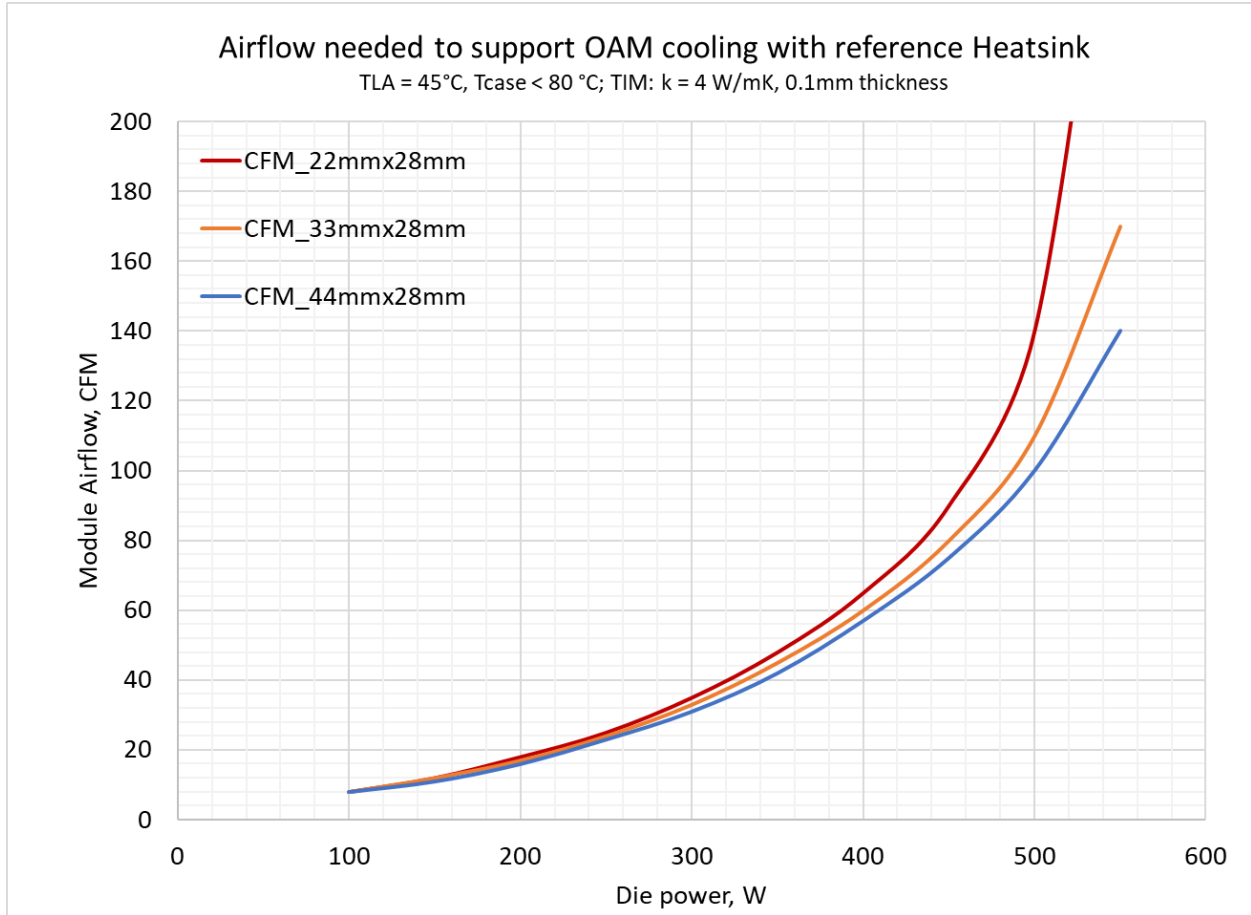


Figure 25 Thermal resistance of reference heatsink V2 with vapor chamber

### 7.5.3 Cooling Limit

Depending on model and application, the OAM may operate at a variety of power levels. However, traditional air-cooled heatsinks may hit their performance limit due to the constraint on heat spreading technologies. Beyond a certain chassis height, fin size, and airflow rate, the improvement on the thermal resistance of the air-cooled heatsink becomes minimal.

Package size also has a significant impact on the cooling capability of OAM modules. Figure 26 provides the airflow needs of a single OAM module at a given approaching temperature, case temperature target, thermal interface material, and die powers. Beyond 120CFM, more airflow towards OAM brings diminishing return, which limits the max OAM power supported. It can also be used to estimate the cooling capability of system design and fan trays.



**Figure 26 Increasing need of airflow for OAM cooling as die power increases**

For a reference OAM in a typical platform with 8x OAMs, shadowing layout, it is observed that the maximum module power that air cooling can support is approximately 450W. Beyond this power limit, advanced cooling solutions are recommended to keep its operation at the hotter part of the operational boundary condition range. These advanced cooling solutions would also be recommended for extended environment boundary conditions. This limit may vary for different products, depending on die size, power distribution, and junction temperature limits.

Open-loop liquid cooling is one of the feasible cooling solutions to support modules of a higher power. To support typical open-loop liquid cooling modules designed for a 1RU (height = 44.45mm) system, it is recommended that OAM vendors limit the maximum distance from the lower surface of the bottom stiffener to the top surface of the die (ASIC/HBM) to within 13mm.





Figure 27 Maximum height of OAM to enable liquid cooling within a 1RU system

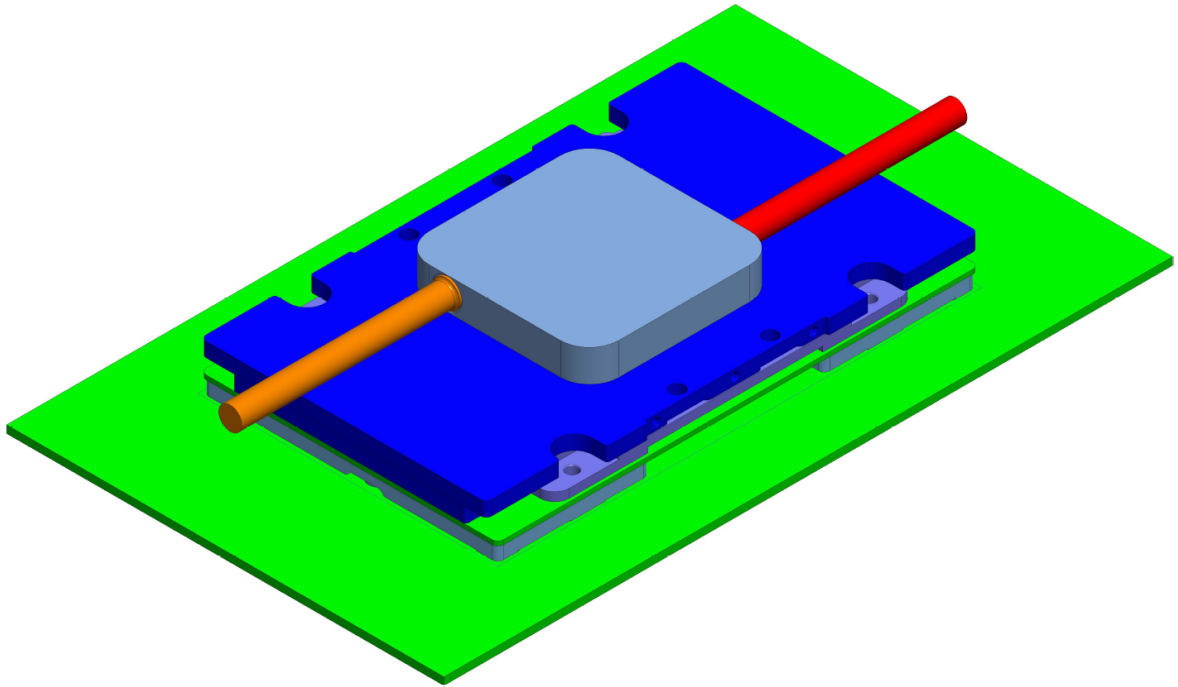


Figure 28 An Example of Open Loop Liquid Cooling setup concept for OAM

A typical open-loop liquid cooling setup (cold plate) for the OAM may include the following parts:

- Cold plate base + thermal interface materials
- Internal Mini/Microchannels
- Internal Manifold
- Coolant inlet/outlet tubes

With a proper coolant supply, open-loop liquid cooling can deliver surface-to-coolant thermal resistance lower than  $0.05^{\circ}\text{C}/\text{W}$ . However, it would require liquid supply and control systems to be established as part of the data center infrastructure.

#### 7.5.4 Heatsink Installation

Many OAM modules use a bare die design, which may be fragile and susceptible to an imbalance of pressure on its surface. The system integrator should contact the OAM supplier for the maximum static and dynamic pressure for the die to guide the installation of the primary heatsink to the module. The

static mounting pressure should also be high enough to enable optimum performance of the TIM material.

We suggest to install following guidelines below:

- Screw head type: Philips #2
- Tightening pattern: Diagonal
- Tightening stage: multiple stages, 2 or 3
- Tightening torques: (TBD)

The mounting pressure of the heatsink is determined by:

- Max pressure the package can sustain
- Min pressure the TIM needs to deliver enough performance

We recommend the mounting pressure range to be 30 ~ 60 psi for OAM with bare die packages. We recommend an initial mounting pressure of 15~30 psi for engineering samples without assembly yield rate learnings. For lid-covered OAM packages, the mounting pressure is yet to be explored.

#### **7.5.5 Thermal Interface Material**

The thermal interface material between the die (ASIC/HBM) and the primary heatsink should maintain a thermal conductivity of at least  $4\text{W/m}\cdot\text{K}$  through the end of its life. This conductivity is equivalent to approximately a  $6^\circ\text{C}$  temperature difference between the heatsink base and the die top surface for a bond line thickness of 0.1mm and heat flux of  $24.4\text{W}/\text{cm}^2$ , which is also equivalent to 300W uniformly distributed over a surface area of 44mm x 28mm.

The maximum warpage of the package should not exceed 0.2mm. It could potentially lead to an average bond line thickness of 0.1mm for the TIM. Varying for different die sizes, TIM could easily contribute  $0.01^\circ\text{C}/\text{W} \sim 0.08^\circ\text{C}/\text{W}$ , up to 50% of total thermal resistance:

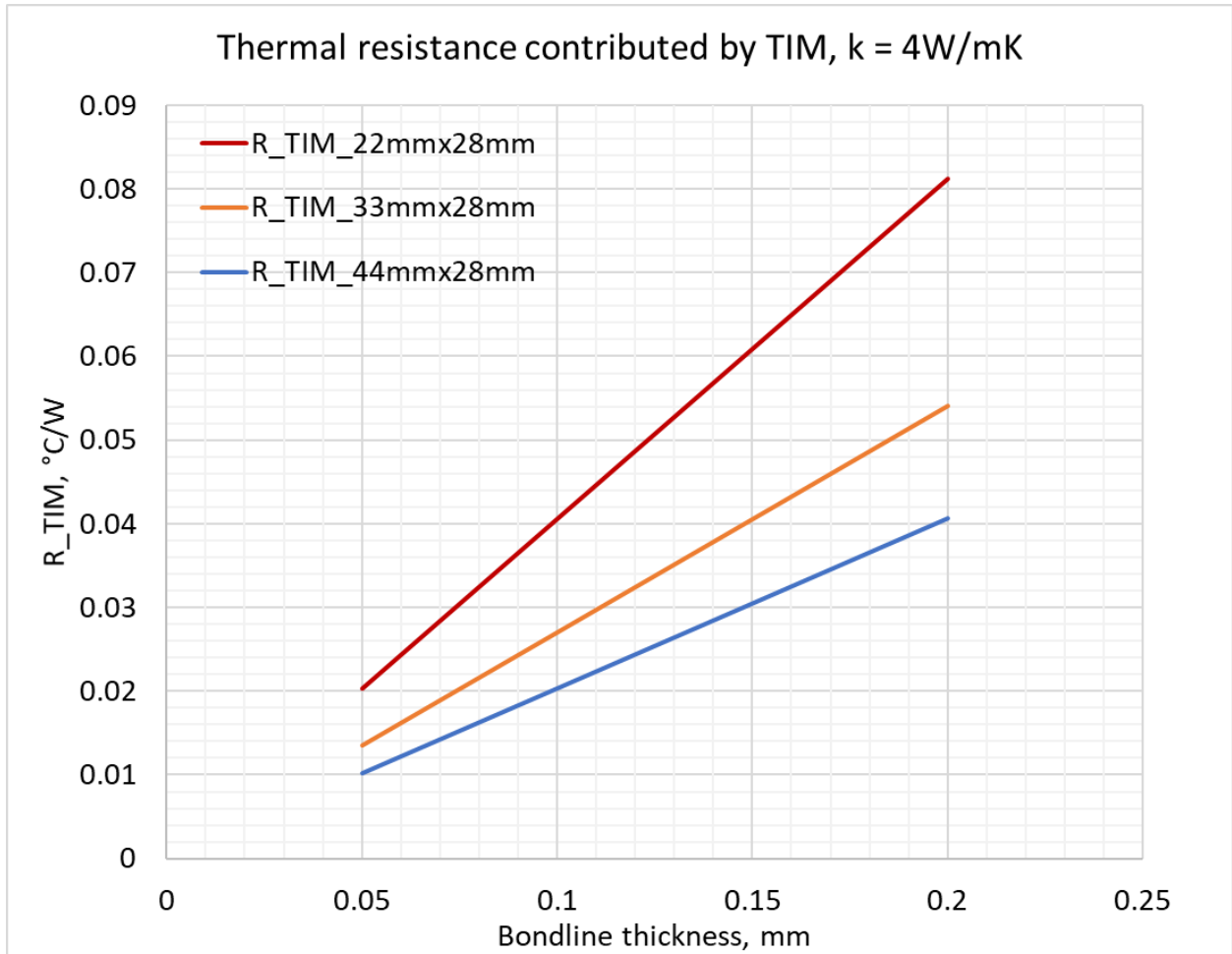


Figure 29 Thermal resistance across TIM layer at different bond line thicknesses

## 8 OAM Electrical Specification

### 8.1 Electrical Connector

The module utilizes two 688pin Molex Mirror Mezz Pro connectors. It is a BGA attached connector. It supports bit rates up to 56Gbps NRZ or 112 Gbps PAM4 in a 90 Ohms nominal impedance  $\pm 5\%$  tolerance, making it compatible with support typical 85 Ohms based interfaces such as PCIe Gen3/4/5 as well as other 100 Ohms based high-speed interfaces. All power and I/O signals are routed through the two connectors down to the system baseboard. The system baseboard should connect these signals to the appropriate circuitry depending on the required feature sets. The below table lists the electrical requirements for the module connectors.

Table 3 Electrical Requirements for Molex Mirror Mezz Pro

Items	Mirror Mezz Pro
Data Rate Support	25/28/32/-Gbps NRZ, 56G/112G PAM4
Connector Impedance	90ohm $\pm 5\%$
Differential pairs per two connectors	172 pairs
Pin Pitch	0.9mm and 1.3mm
Current Rating per pin @80C ambient temp, 1.5oz copper	1A/pin after 20% derating
Max Voltage Application	30V AC (OAM supports 60V after Molex's pin assignment review)
Connector insertion cycles	100cycles
Withstand voltage	500V min
Low-Level Contact Resistance (max initial):	30m $\Omega$ for 5mm stack height
Insulation resistance	1-M $\Omega$ min
Intra-pair skew	$\leq 5$ ps

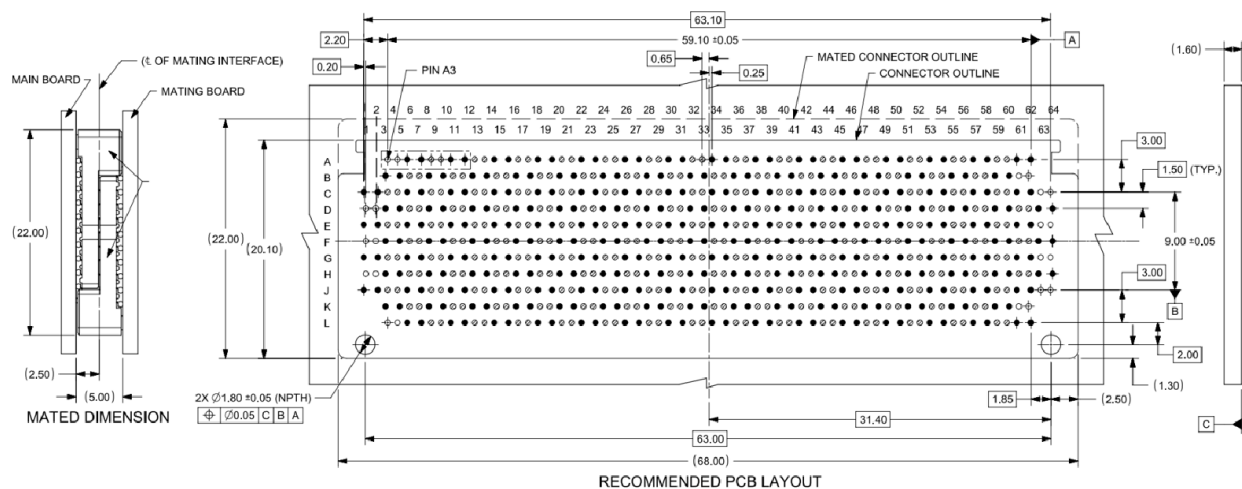


Figure 30 Mirror Mezz Pro Connector Footprint

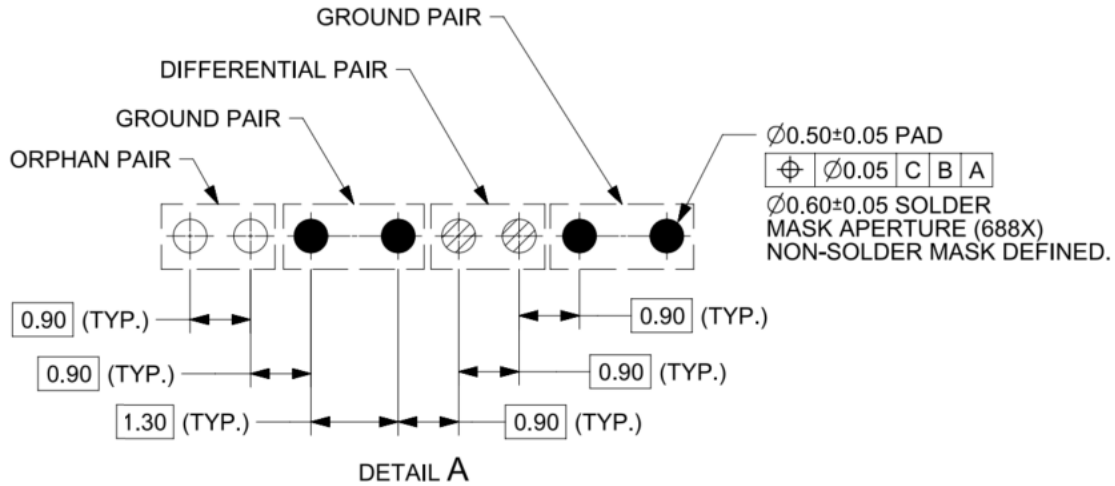


Figure 31 Mirror Mezz Pro Connector Pin to Pin Pitch

## 8.2 OAM Connector Pinout Quadrants

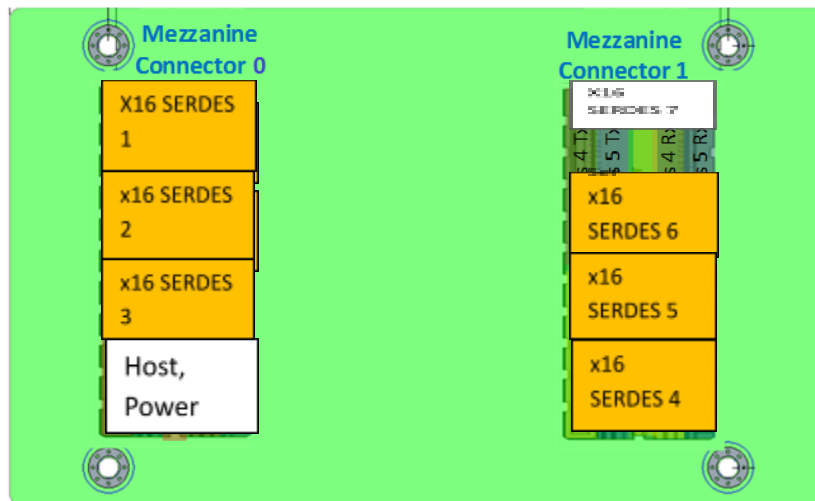


Figure 32 Mezzanine Connectors Pinout Quadrants

The OAM Connector 0 has the following interfaces:

- 54V/48V and 12V input power
- x16 SerDes to connect to host
- 3x16 SerDes for the accelerator to accelerator communication
  - X16 may split into sub-links like 2\* x8s or 4\* x4s or 16\*x1s.
  - If the ASIC or ASICs on the module only support x8 or x4 per SerDes, it should start from Lane0 from the SerDes, e.g., lane [7:0] or lane [3:0].
  - We do not recommend lane reversal support on the baseboard due to modules having the option to be 1X16 links or 2X8 or 4X4 links.

- Other single-ended signals, like PRESNT#, SMBus, GPIOs etc.

The OAM Connector 1 has the following interfaces:

- Power pins for 3.3V
- Other single-ended signals like JTAG, GPIOs etc.
- Up to 4 SerDes for the accelerator to accelerator communication or other purposes:
  - SerDes 4, 5, 6, and 7 are up to x16 lanes which can split into X8s, X4s, or X1s.
- SerDes 7 may be defined for different use cases:
  - This link could be the 7<sup>th</sup> SerDes for some cases to have a fully connected interconnect between the modules
  - It could be the 2nd link to host for the ASIC(s) on the module, e.g., a full x16 link, 2x8, or 4x4 links.
  - Or it could be a unique defined link by some ASICs. E.g., it could be a downstream port for the ASIC on the module.

### 8.3 OAM Pinout Description

The detailed pin mapping to connectors is in the separated spreadsheet. This section only shows the pin list and description.

Table 4 OAM Pinouts

Signal	IO Type (Module Direction POV)	Description	Voltage	Required or Optional	Total Diff Pins	Total Single Pins	Conn 0 or 1
P48V	Power (Input)	44V-59.5V main voltage for high power applications. Up to 700W when $V_{in} \geq 44V$ . The module should operate at 40V to 44V but at lower power (ex. baseboard to drive PWRBRK# for $V_{in} < 44V$ if supported).	44V-59.5V	Required		16	Conn0
P12V1	Power (Input)	12V mandatory module Infrastructure Power. Up to 50W	12V	Required		5	Conn0
P12V2	Power (Input)	12V main voltage for low power applications. Up to 300W. For 12V baseboard/module designs, P12V1 and P12V2 can be shorted	12V	Required for P12V based OAM		27	Conn0

		together for up to 350W combined power					
<b>P3V3</b>	Power (Input)	3.3V Main voltage. Up to 5W	3.3V	Required		2	Conn0
<b>PVREF</b>	Power (Output)	Low voltage output for GPU/ASIC sideband I/O reference on baseboard components. The module should provision a minimum of 0.5A on the baseboard. $V_{ref}$ range: 1.2V ~ 3.3V.	$V_{ref}$	Required		2	Conn0
<b>PETp/n [15:0]</b>	CML (Output)	PCIe or equivalent host link Transmit differential pairs. Module Transmit, Host Receive. Note: AC coupling caps must be placed on the baseboard side.		Required		16	Conn0
<b>PERp/n [15:0]</b>	CML (Input)	PCIe or equivalent host link Receive differential pairs. Module Receive, Host Transmit. Note: AC coupling caps must be placed on the baseboard side.		Required		16	Conn0
<b>SERDES_1Tp/n [15:0]</b>	CML (Output)	SerDes link 1 Transmit differential pairs. AC caps must be placed on Module/die (if required)		Required		16	Conn0
<b>SERDES_1Rp/n [15:0]</b>	CML (Input)	SerDes link 1 Receive differential pairs.		Required		16	Conn0
<b>SERDES_2Tp/n [15:0]</b>	CML (Output)	SerDes link 2 Transmit differential pairs. AC caps must be placed on Module/die (if required)		Required		16	Conn0
<b>SERDES_2Rp/n [15:0]</b>	CML (Input)	SerDes link 2 Receive differential pairs.		Required		16	Conn0
<b>SERDES_3Tp/n [15:0]</b>	CML (Output)	SerDes link 3 Transmit differential pairs. AC caps must be placed on Module/die (if required)		Required		16	Conn0

<b>SERDES_3Rp/n [15:0]</b>	CML (Input)	SerDes link 3 Receive differential pairs.		Required	16		Conn0
<b>SERDES_4Tp/n [15:0]</b>	CML (Output)	SerDes link 4 Transmit differential pairs. AC caps must be placed on Module/die (if required)		Required	16		Conn1
<b>SERDES_4Rp/n [15:0]</b>	CML (Input)	SerDes link 4 Receive differential pairs.		Required	16		Conn1
<b>SERDES_5Tp/n [15:0]</b>	CML (Output)	SerDes link 5 Transmit differential pairs. AC caps must be placed on Module/die (if required)		Required	16		Conn1
<b>SERDES_5Rp/n [15:0]</b>	CML (Input)	SerDes link 5 Receive differential pairs.		Required	16		Conn1
<b>SERDES_6Tp/n [15:0]</b>	CML (Output)	SerDes link 6 Transmit differential pairs. AC caps must be placed on Module/die (if required)		Required	16		Conn1
<b>SERDES_6Rp/n [15:0]</b>	CML (Input)	SerDes link 6 Receive differential pairs.		Required	16		Conn1
<b>SERDES_7Tp/n [15:0]</b>	CML (Output)	SerDes Link 7 Transmit differential pairs. Alternate link for secondary PCIe Bus. AC caps must be placed on Module/die (if required)		Required	16		Conn1
<b>SERDES_7Rp/n [15:0]</b>	CML (Input)	SerDes Link 7 Receive differential pairs. Alternate link for secondary PCIe Bus. AC caps must be placed on Module/die (if required)		Required	16		Conn1
<b>PE_REFCLKp/n</b>	Diff (Input)	PCIe Reference Clock. 100MHz PCIe Gen 5 compliant.		Required	1		Conn0
<b>AUX_100M_RE FCLKp/n</b>	Diff (Input)	Auxiliary Reference Clock. 100MHz PCIe Gen 5 compliant		Required	1		Conn1
<b>DWN_REFCLKp /n</b>	Diff (Output)	Downstream Reference Clock. Vendor specific.		Optional	1		Conn1
<b>AUX_156M_RE FCLKp/n</b>	Diff (Input)	156.25MHz Auxiliary Reference Clock,		Optional	1		Conn1



		+/-50ppm. Vendor specific. System integrator may collect jitter requirement from OAM suppliers.					
<b>PERST#</b>	(Input)	CEM Compliant PCIe Reset	3.3V	Required		1	Conn0
<b>WARMRST#</b>	(Input)	Warm Reset	V <sub>ref</sub>	Optional		1	Conn0
<b>DWN_PERST#</b>	Push-pull (Output)	Down device PCIe Reset. Vendor specific.	3.3V	Optional		1	Conn1
<b>HOST_PWRGD</b>	Push-Pull (Input)	Host power is good. Active high when P48V, P12V1/P12V2, P3V3 voltages are stable and within specifications. It is considered the "Power Enable" signal for the module. 10k PD on the baseboard.	3.3V	Required		1	Conn0
<b>MODULE_PWRGD</b>	Push-pull (Output)	Module power is good. Active high when the module has completed its power-up sequence and is ready for PERST# de-assertion. 100k PD on the baseboard.	3.3V	Required		1	Conn0
<b>PWRBRK#</b>	Pull-up (Input)	Emergency power reduction. CEM Compliant Power Break. 47K PU on the module	3.3V	Required		1	Conn0
<b>PWRRDT#[1:0]</b>	Pull-up (Input)	Power Reduction GPIO to instruct OAM to go particular stage to reduce power 11 - default state L0, normal power 10 - L1, 1st level power reduction. 01 - L2, 2nd level power reduction. 00 - L3, max power reduction. Specific OAM product specifications define details. 47K PU on the module	3.3V	Optional		2	Conn1

<b>THERMTRIP#</b>	Open-drain (Output)	Catastrophic thermal event for module components. Active low and latched by the Module logic. Released when the baseboard power cycles the module input voltages 10K PU on the module. See Note for OAM power rails requirement.	3.3V	Required		1	Conn1
<b>MODULE_ID[4:0]</b>	Pull-up (Input)	Module node identifier (e.g. Module #0, #1,...#n). Refer to Section 9.1 for details. 47K PU on the module. The supplier decides to pull up the reference voltage. The baseboard has 100ohm PD for logic 0 and leaves it floating for logic 1.	3.3V or $V_{ref}$	Required		5	Conn0
<b>LINK_CONFIG[4:0]</b>	Pull-up (Input)	Mezz Module Host Interface/SerDes Link Configuration and topology. See Section 9.3 for details. 47K PU on the module. The supplier decides to pull up the reference voltage. Baseboard pulls low them for logic 0 and leaves them floating for logic 1.	3.3V or $V_{ref}$	Required		5	Conn1
<b>PE_BIF[1:0]</b>	(Output)	x16 Host Interface Bifurcation Configuration. 00 = one x16 PCIe host interface 01 = bifurcation into two x8 PCIe host interfaces 10 = bifurcation into four x4 PCIe host interfaces 11 = reserved	$V_{ref}$	Required		2	Conn1

		The module has 10K PU for logic “1” or 1K PD for logic “0”. The baseboard has 100k PU.					
<b>PLINK_CAP</b>	(Output)	"P" Port Module Capability support: '0' = PCIe only support '1' = Alternate protocol supported The host system requests an alternate host link protocol by pulling up LINK_CONFIG[0], and the module informs the system of protocol support on the "P" link via this pin. The module has 10K PU for logic “1” or 1K PD for logic “0”. The baseboard has 100k PU.	V <sub>ref</sub>	Required		1	Conn1
<b>SMBus_D</b>	Open-drain (I/O)	I2C/SMBus data	3.3V	Required		1	Conn0
<b>SMBus_CLK</b>	(Input)	I2C/SMBus clock	3.3V	Required		1	Conn0
<b>SMB_ALERT#</b>	Open-drain (Output)	alert indication	3.3V	Optional		1	Conn0
<b>I2C_D</b>	Open-drain (I/O)	Master I2C/SMBus data. PU on OAM.	V <sub>ref</sub>	Optional		1	Conn0
<b>I2C_CLK</b>	Open-drain (Output)	Master I2C/SMBus clock. PU on OAM.	V <sub>ref</sub>	Optional		1	Conn0
<b>UART_TXD</b>	Push-pull (Output)	Serial Port Transmit	3.3V	Optional		1	Conn0
<b>UART_RXD</b>	(Input)	Serial Port Receive	3.3V	Optional		1	Conn0
<b>JTAG0_TRST</b>	(Input)	Low Voltage ASIC/GPU JTAG Test Reset	V <sub>ref</sub>	Required		1	Conn0
<b>JTAG0_TMS</b>	(Input)	Low Voltage ASIC/GPU JTAG Test Mode Select	V <sub>ref</sub>	Required		1	Conn0
<b>JTAG0_TCK</b>	(Input)	Low Voltage ASIC/GPU JTAG Test Clock	V <sub>ref</sub>	Required		1	Conn0

<b>JTAG0_TDO</b>	Push-pull (Output)	Low Voltage ASIC/GPU JTAG Test Output	$V_{ref}$	Required		1	Conn0
<b>JTAG0_TDI</b>	(Input)	Low Voltage ASIC/GPU JTAG Test Input	$V_{ref}$	Required		1	Conn0
<b>JTAG1_TRST</b>	(Input)	High Voltage JTAG Test Reset	3.3V	Optional		1	Conn1
<b>JTAG1_TMS</b>	(Input)	High Voltage JTAG Test Mode Select	3.3V	Optional		1	Conn1
<b>JTAG1_TCK</b>	(Input)	High Voltage JTAG Test Clock	3.3V	Optional		1	Conn1
<b>JTAG1_TDO</b>	Push-pull (Output)	High Voltage JTAG Test Output	3.3V	Optional		1	Conn1
<b>JTAG1_TDI</b>	(Input)	High Voltage JTAG Test Input	3.3V	Optional		1	Conn1
<b>CONN1_INITMODE</b>	Push-pull (Output)	QSFP-DD Connector 1 Module Initialization mode	$V_{ref}$	Optional		1	Conn1
<b>CONN1_INT#</b>	(Input)	QSFP-DD Connector 1 Module Interrupt	$V_{ref}$	Optional		1	Conn1
<b>CONN1_MODPRS#</b>	(Input)	QSFP-DD Connector 1 Module Present	$V_{ref}$	Optional		1	Conn1
<b>CONN1_MODSEL#</b>	Push-pull (Output)	QSFP-DD Connector 1 Module Select	$V_{ref}$	Optional		1	Conn1
<b>CONN1_RESET#</b>	Push-pull (Output)	QSFP-DD Connector 1 Module Reset	$V_{ref}$	Optional		1	Conn1
<b>CONN1_GREEN_LED</b>	Push-pull (Output)	QSFP-DD Connector 1 GREEN STATUS LED	$V_{ref}$	Optional		1	Conn1
<b>CONN1_YELLOW_LED</b>	Push-pull (Output)	QSFP-DD Connector 1 YELLOW STATUS LED	$V_{ref}$	Optional		1	Conn1
<b>CONN2_INITMODE</b>	Push-pull (Output)	QSFP-DD Connector 2 Module Initialization mode	$V_{ref}$	Optional		1	Conn1
<b>CONN2_INT#</b>	(Input)	QSFP-DD Connector 2 Module Interrupt	$V_{ref}$	Optional		1	Conn1
<b>CONN2_MODPRS#</b>	(Input)	QSFP-DD Connector 2 Module Present	$V_{ref}$	Optional		1	Conn1
<b>CONN2_MODSEL#</b>	Push-pull (Output)	QSFP-DD Connector 2 Module Select	$V_{ref}$	Optional		1	Conn1
<b>CONN2_RESET#</b>	Push-pull (Output)	QSFP-DD Connector 2 Module Reset	$V_{ref}$	Optional		1	Conn1
<b>CONN2_GREEN_LED</b>	Push-pull (Output)	QSFP-DD Connector 2 GREEN STATUS LED	$V_{ref}$	Optional		1	Conn1
<b>CONN2_YELLOW_LED</b>	Push-pull (Output)	QSFP-DD Connector 2 YELLOW STATUS LED	$V_{ref}$	Optional		1	Conn1
<b>PRSNT0#</b>	Pull-down (Output)	Module present pin connector 0.	GND	Required		1	Conn0

		1K PD on the module. The baseboard has 10k PU to STBY power rail of management chip.					
<b>PRSNT1#</b>	Pull-down (Output)	Module present pin connector 1. 1K PD on the module. The baseboard has 10k PU to STBY power rail of management chip.	GND	Required		1	Conn1
<b>SCALE_DEBUG_EN</b>	Push-pull (Output)	At-a-scale debug enable on the module. Isolates any baseboard JTAG debug path when a logic high. The baseboard has 4.7K PU as default.	3.3V	Optional		1	Conn1
<b>DEBUG_PORT_PRSNT#</b>	(Input)	Presence signal for physical debug presence in the baseboard. Low active. This pin is used to disable intrusive debug capabilities for security reasons. Refer to 11.8.3.	3.3V	required		1	Conn1
<b>MNGMT_LINK_0Tp/n</b>	CML (Output)	Vendor-specific module to module management link port 0 transmit. It is required for some OAMs. Check with the OAM supplier.		Optional		1	Conn1
<b>MNGMT_LINK_0Rp/n</b>	CML (Input)	Vendor-specific module to module management link port 0 receive. It is required for some OAMs. Check with the OAM supplier.		Optional		1	Conn1
<b>MNGMT_LINK_1Tp/n</b>	CML (Output)	Vendor-specific module to module management link port 1 transmit. It is required for some OAMs. Check with the OAM supplier.		Optional		1	Conn1

<b>MNGMT_LINK 1Rp/n</b>	CML (Input)	Vendor-specific module to module management link port 1 receive. It is required for some OAMs. Check with the OAM supplier.		Optional	1		Conn1
<b>TEST[0:4]</b>	(Input)		$V_{ref}$	Optional		5	Conn0
<b>TEST[5:9]</b>	Push-pull (I/O)		$V_{ref}$	Optional		5	Conn0
<b>TEST[10:14]</b>	Push-pull (I/O)		$V_{ref}$	Optional		5	Conn1
<b>MANF_MODE#</b>	(Input)	Manufacturing Mode 1: Normal operation 0: Module enter into manufacturing mode. The baseboard has 4.7k PU.	3.3V	Optional		1	Conn0
<b>FW_RECOVERY #</b>	(Input)	On board manageability boot recovery mode 1: Normal operation 0: Firmware Recovery boot mode The baseboard has 4.7k PU.	3.3V	Optional		1	Conn0
<b>TEST_MODE#</b>	(Input)	Compliance Test Mode 1: Normal operation 0: ASIC/GPU enter into electrical compliance mode. Baseboard has 4.7k PU	$V_{ref}$	Optional		1	Conn0
<b>RFU</b>		Reserved for future use				4	Conn0
<b>RFU</b>		Reserved for future use				35	Conn1

**Note:**

- 1) When a catastrophic thermal event (THERMTRIP#) occurs, OAM should shut down all its onboard power rails.
- 2) The baseboard should do the following:
  - a. Turn off all input clocks
  - b. Tristate all OAM input GPIO
  - c. Turn off all input power rails to OAM

## GPIO Recommended Operating Conditions

	Description	MIN	MAX	Unit
$V_{3V3}$	IO reference voltage	3.135	3.465	V
$V_{ref}$	2 <sup>nd</sup> IO reference voltage, ranging from 1.2V to 3.3V	$0.95 \times V_{ref}$	$1.05 \times V_{ref}$	V
$V_{IH-3V3}$	High level of IO refer to 3.3V	$0.7 \times V_{3V3}$	3.465	V
$V_{IL-3V3}$	Low level of IO refer to 3.3V	-0.5	$0.3 \times V_{3V3}$	V
$V_{IH-Vref}$	High level of IO refer to Vref	$0.7 \times V_{ref}$	$V_{ref}$	V
$V_{IL-Vref}$	Low level of IO refer to Vref	-0.5	$0.3 \times V_{ref}$	V

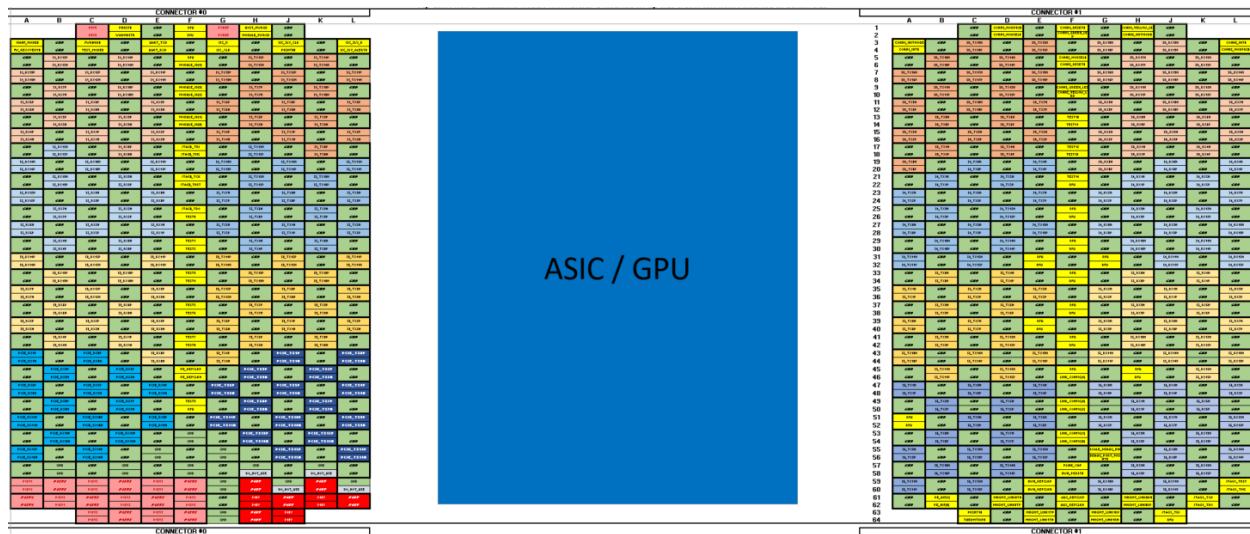


Figure 33 – Mezzanine Connector Pin map

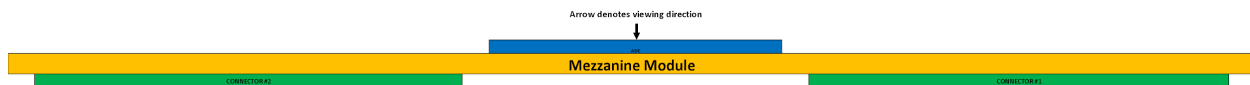


Figure 34 – Mezzanine Connector Pin Out View Reference

## 8.4 OAM Power Profiles

This section defines the maximum thermal design power (TDP) the module can support and the excursion design power (EDP).

### 8.4.1 Thermal Design Power TDP

The module supports up to 350W TDP if the input nominal voltage is 12V. The module supports up to 700W if the input nominal voltage is 48V or 54V.

The OAM baseboard supplies power to the module through the Mirror Mezz Pro Connector0 power pins. There are 3 power rails defined in this document to accommodate both 12V and 48V (or 54V) modules. The current capability and power status are in the table below. The power is available on state S0 only. Only five P12V power pins are mandatory when the supply power is 48V (16 pins), and the rest of the P12V pins can be NC. When the baseboard supply power is 12V, P48V can be NC. The baseboard can supply all 3 power rails and supports both 12V and 48V modules.

**Table 5 Power Rails**

Power Rail	Voltage Tolerance	# of pins	Current Capability	Status
P12V	11V min to 13.2V max	27	27A (when at 11V)	Normal Power
P12V Mandatory	11V min to 13.2V max	5	5A (when at 11V)	Normal Power
P48V	44V min to 60V max	16	16A (when at 44V)	Normal power
P3.3V	3.3V±10%(max)	2	2A	Normal power

Note: To support even higher TDP OAMs, we can further bypass 12V to provide more 48V and vice versa.

### 8.4.2 Excursion Design Power EDP

System baseboard designers should be sure to support the OAM’s excursion design power (aka EDP). The OAM VR electrical design must handle the instantaneous peak power short period (usually on the order of a  $\mu$ s) with a low duty cycle. The VR’s thermal design should be robust enough to handle lower power EDP levels (e.g., 1.1x TDP) for ms level interval without asserting VR HOT over-temperature alert. The system integrator should closely work with the module suppliers to ensure that the baseboard supplies enough power without triggering under-voltage protection.

**Table 6 Excursion Design Power Example**

EDP	Duration
2x TDP	$\leq 20\mu$ s
1.6x TDP	$\leq 2$ ms
1.5x TDP	$\leq 5$ ms
1.2x TDP	$\leq 10$ ms
1.1x TDP	$\leq 20$ ms

### 8.5 System power sequencing

System designers should follow the below power sequence requirement to implement the design. It is recommended to check with each specific module specification to ensure the modules work correctly.



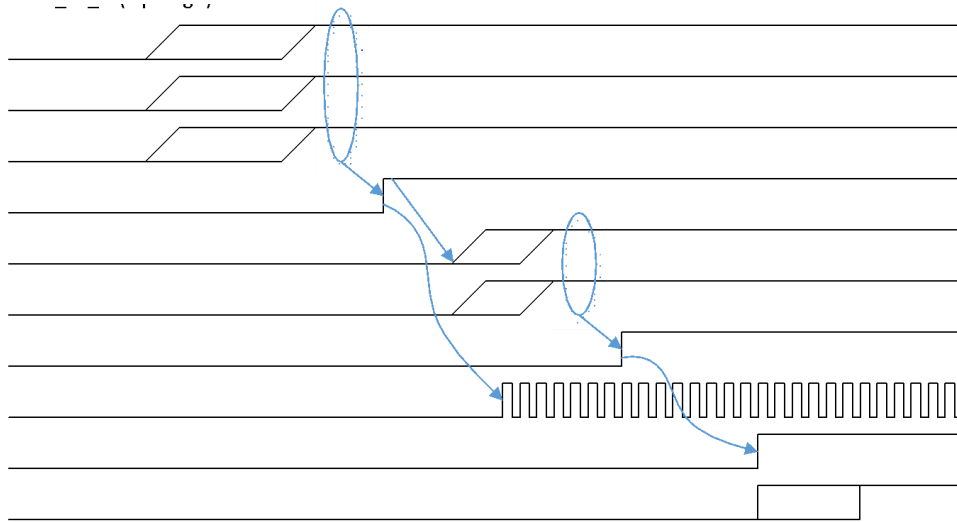


Figure 35 OAM Power Up Sequence

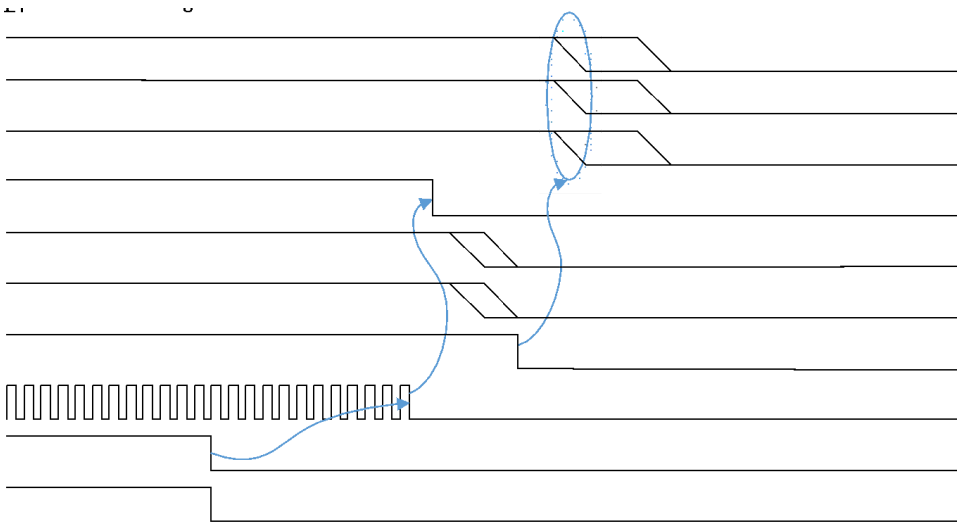


Figure 36 OAM Power-Down Sequence

Notes:

- 1) If the OAMs with the baseboard is in the host system's disaggregated design, the HOST\_PWRGD is the baseboard power good indication signal.
- 2) All voltages on the baseboard that OAM plugs into must be within specification before HOST\_PWRGD is asserted.
- 3) HOST PWRGD is the enable signal to the voltage regulators on the OAM.
- 4) As the voltage planes on the module ramp up, the reference clocks from the baseboard will begin to run.

- 5) After all the voltages on the module are within specification, the module asserts MODULE\_PWRGD to the baseboard.
- 6) The baseboard should tri-state all OAMs single-ended input signals before MODULE\_PWRGD is asserted. Note that input signals required for the power sequence should be driven accordingly.
- 7) At least 100ms after MODULE\_PWRGD assertion, the baseboard will de-assert the PCIe reset signal(PERST#) to the module.
- 8) The optional WARMRST# signal de-asserts simultaneously or later than the PERST# signal is de-asserted.

## 8.6 OAM Insertion Loss

The module interconnection channel total insertion loss from silicon die to mated connector should not exceed -8dB at 28GHz. The system integrator may contact the module supplier for details about the interconnection channel insertion loss and plan system baseboard design accordingly. For other speeds over 14.025GHz, the system integrator should closely work with the module supplier to determine the loss budget on the module and the baseboard.

Total Tx or Rx loss on Module +mated Mezz Connectors @28Ghz	up to 8dB
---	-----------

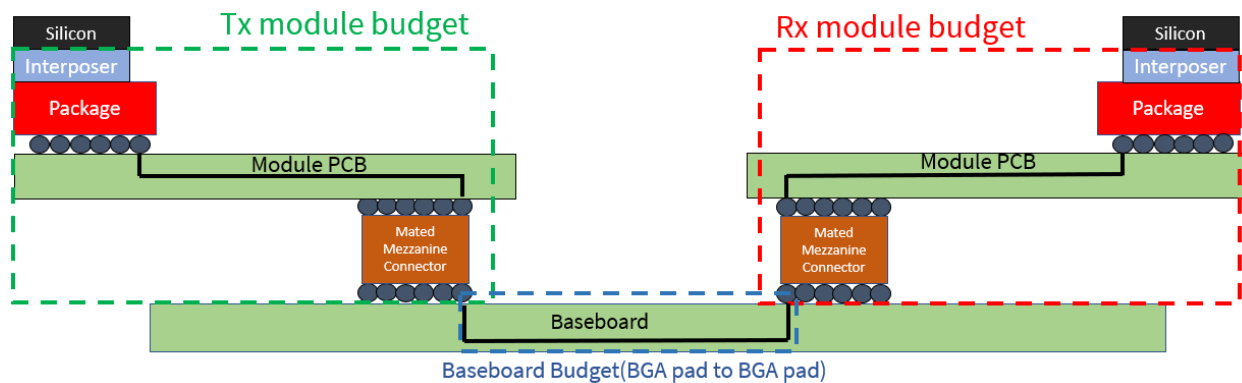


Figure 37 Channel loss Budget (PCB-only Topology)

**Total channel loss budget = Tx module + baseboard + Rx module**

Example:

Total channel loss budget = 30 dB (28GHz)

- Tx module = 8 dB
- Rx module = 8 dB
- Baseboard budget = 30 dB – 8 dB – 8 dB = 14 dB

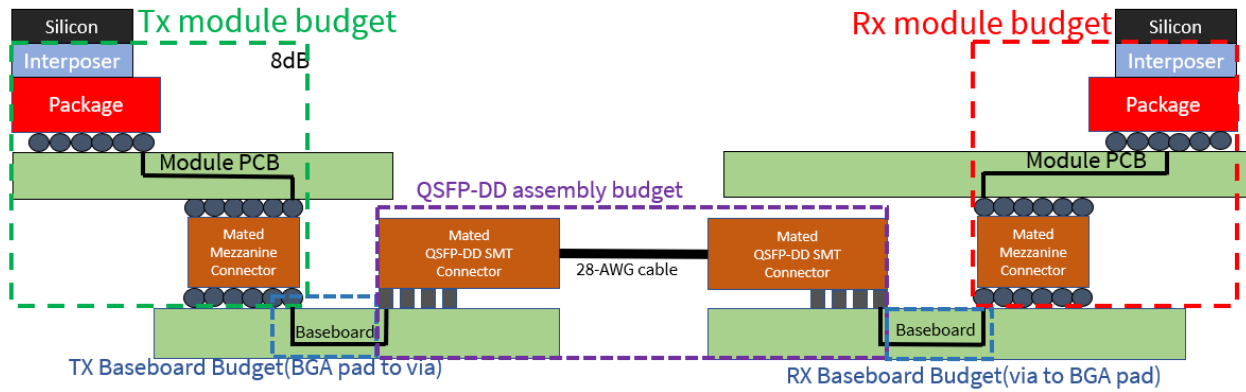


Figure 38 Channel loss budget (Cabled Topology)

**Total channel loss budget = Tx module + Tx baseboard + QSFP-DD assembly + Rx baseboard + Rx module**

Example:

Total channel loss budget = 30 dB (28 GHz)

- Tx module = 8 dB
- Rx module = 8 dB
- QSFP-DD = 5 dB
- Tx + Rx baseboard budget = 30 dB – 8 dB – 8 dB – 5.0 dB = 9dB

### 8.7 Management link

Management links 0/1 are defined for OAM to communicate with each other. When the host interface is PCIe, management links are routed in a ring as illustrated in the following diagrams with Management link 0 on one module connecting to management link 1 on the next module.

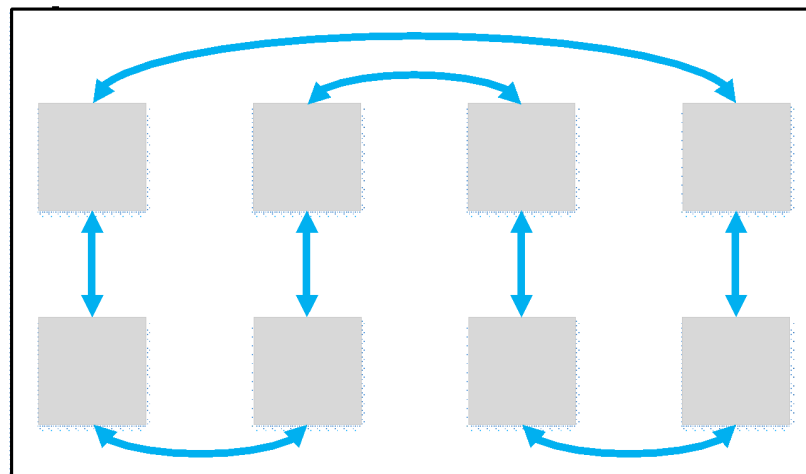


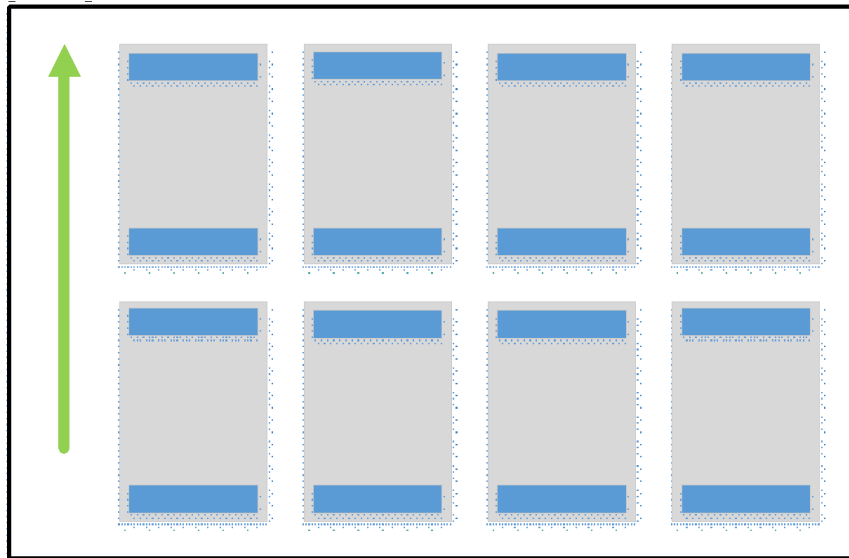
Figure 39 Management Link Routing Guidance

## 9 OAM Interconnect Topologies

This section describes the recommended interconnection topology for a system with 4, 8, and 16 OAMs.

### 9.1 Module ID

The following figure shows the `MODULE_ID[4:0]` strapping for the physical orientation of modules when 8 interconnected OAMs are used.



**Figure 40 Required `MODULE_ID[4:0]` assignments for baseboards with 8 interconnected modules**

Detail port to port assignment is based on system placement and routing length. Module to module interconnect may decrease to 4 ports if the module only supports 4. Module to module interconnect link may only utilize 8 lanes if the module defines 8 lanes per link.

The following Figure shows the required `MODULE_ID[4:0]` assignments when only 4 modules are connected as two rows of two.

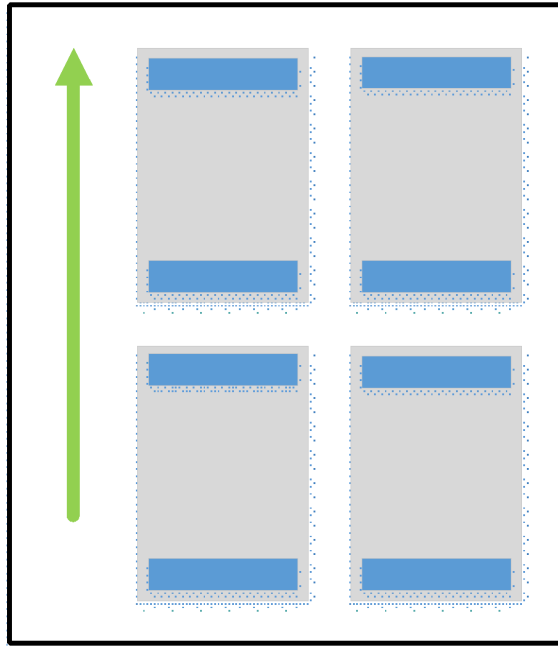


Figure 41 MODULE\_ID[4:0] assignments when four only in two rows of two

## 9.2 Interconnect Topology

This section describes different interconnect topologies and routing guidance for 8 OAMs with varying numbers of the port. If all 7 ports are configured and routed as x16, there is no additional port(s) for expansion. To reserve expansion port(s), we suggest limiting onboard Interconnect links up to x8. 2<sup>nd</sup> half of port 1(x8, also referred to as 1H) is reserved for expansion by default. 2<sup>nd</sup> half of ports 4,6,7 are used in X8 based full connected topology at section 9.2.4.

### 9.2.1 Hybrid Cube Mesh (HCM) for 6 ports per OAM

The below figure shows an example topology (Hybrid Cube Mesh) of 8 modules in a baseboard.

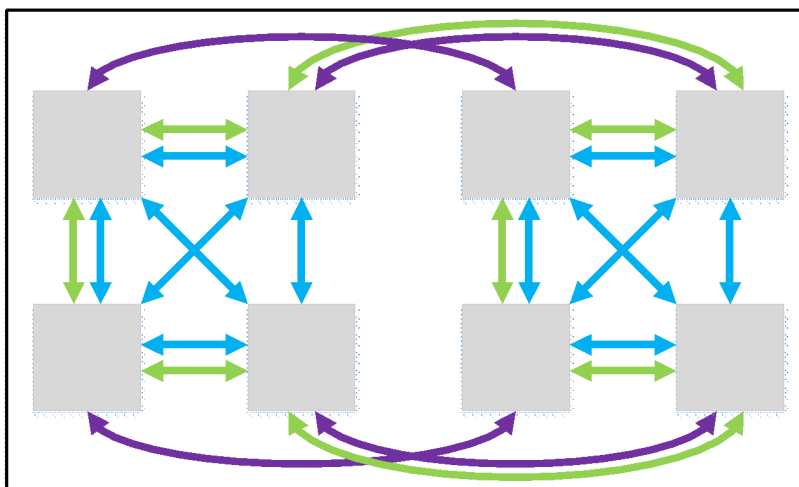


Figure 42 Topology Example for Modules with 3/4/6 ports – Hybrid Cube Mesh

The interconnect topology in this Figure supports the following OAM module interconnects:

- 3 links and two fully connected quads using links: 1, 3, and 4
- 4 link Hybrid Cube Mesh using links: 1, 3, 4, and 6
- 6 link Hybrid Cube Mesh using links: 1, 2, 3, 4, 5, and 6

Here is the routing suggestion for Hybrid Cube Mesh:

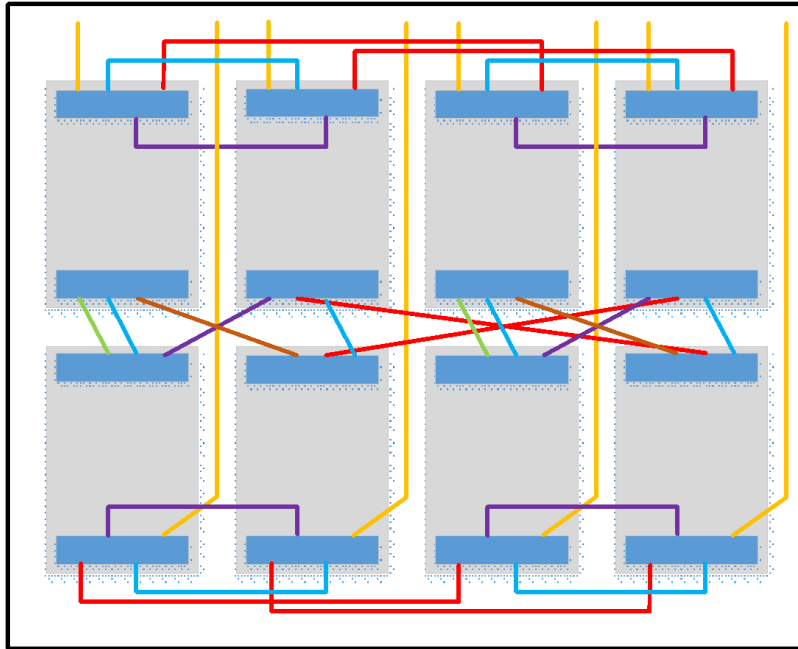


Figure 43 6 Ports Hybrid Cube Mesh Routing Recommendation

### 9.2.2 Almost Fully Connected

Depending on different workloads, if the module has 6 links, the other topology considered is Almost Fully Connected (also called Chordal Ring). Each module connects to the other 6 of the modules with 1 link. The figure below illustrates the topology:



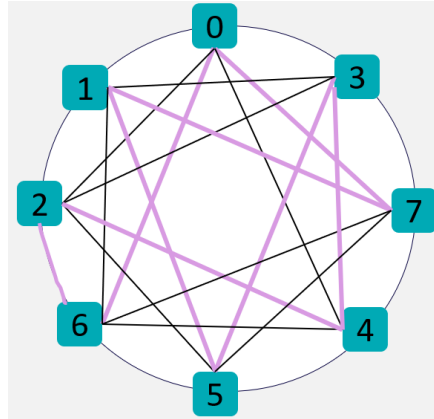


Figure 44 Almost Fully Connected Topology

The interconnect topology below figure supports the following OAM module interconnects:

- 6 x16 links Chordal Ring (Almost Fully Connected) using links: 1, 2, 3, 4, 5, and 6

Here is the routing suggestion:

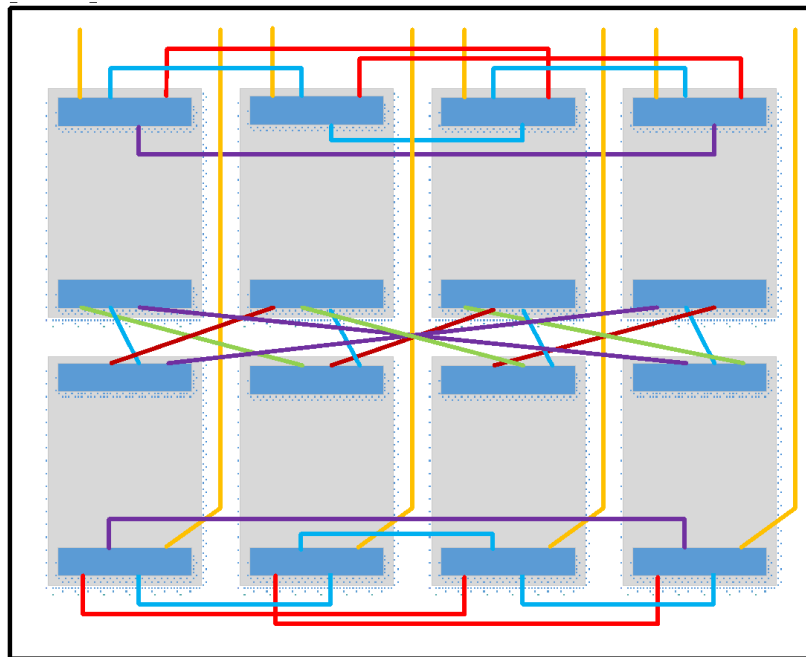


Figure 45 Routing Recommendation for Almost Fully Connected Topology

### 9.2.3 Hybrid Cube Mesh for 8 ports per OAM

The Figure below shows an example of 8 ports topology (Hybrid Cube Mesh) of 8 modules in a baseboard. Please follow port mapping to design OAM to be able to fit in the universal OAM baseboard. Port 4/6 are connected through QSFP-DD cables for a single 8 module system. These QSFP-DD cables can also be used for expansion (scale-out).

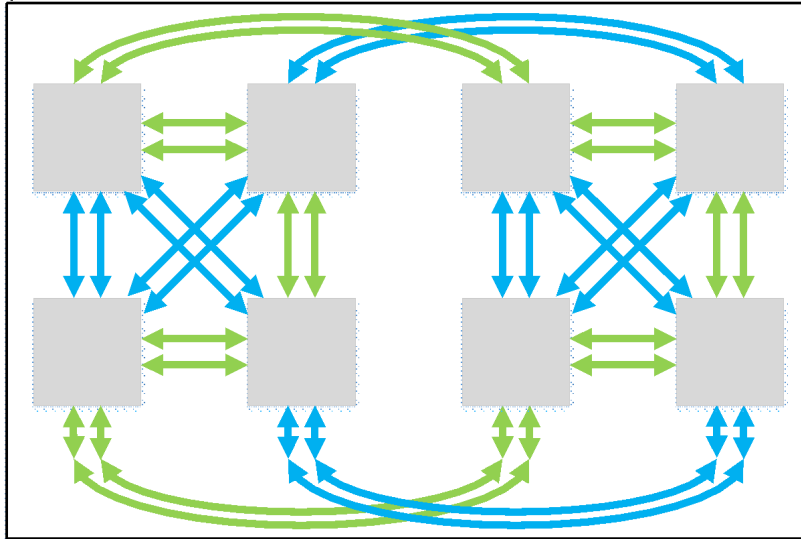


Figure 46 8-port Hybrid Cube Mesh Topology

Here is the routing suggestion: total 4 layers, two layers for TX two layers for RX. Port 4/6 connects through cables.

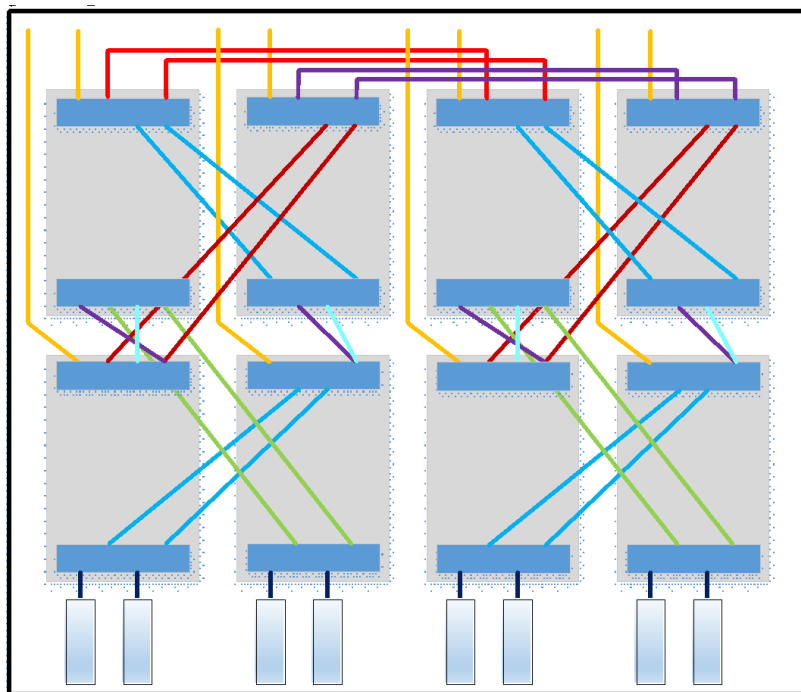


Figure 47 8-port HCM topology routing guide

### 9.2.4 Fully Connected

If the module has 7 or more links, each can directly communicate with the other 7 modules. The topology is fully connected. Each link can be up to X16 in FC topology (no extra link or port for scale-out if it's X16 per the link here).

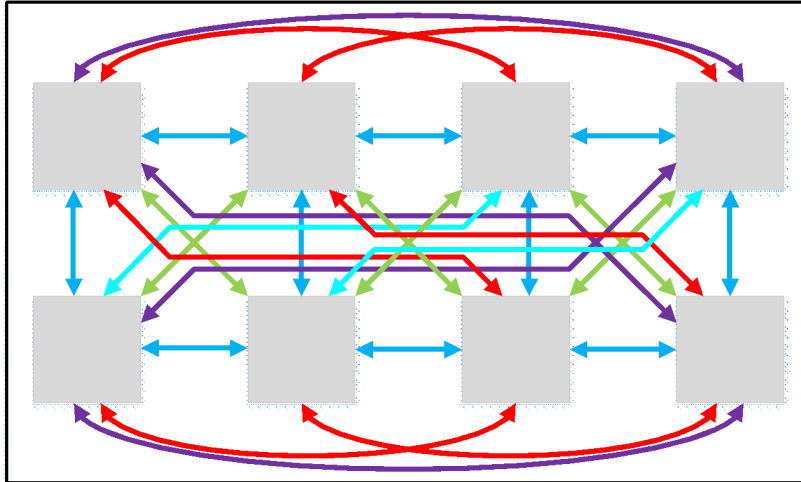


Figure 48 Fully Connected Topology

Here is the routing suggestion for 7X16 links fully connected topology:

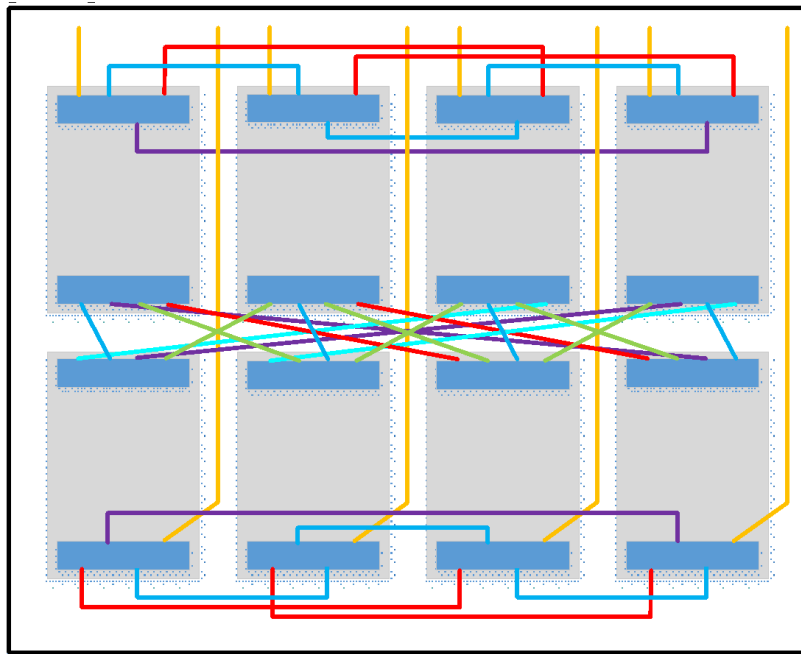


Figure 49 Routing Recommendation for Fully Connected Topology

### 9.2.5 Combined FC/6-Port HCM Topology

For fully connect with expansion consideration, the baseboard link is suggested to route as X8( 1<sup>st</sup> X8 of each port, 1L-7L), leaving 2<sup>nd</sup> X8 of each SerDes port for expansion or embedding other topology. Here is 7X8 fully connected topology combined with 6X8 hybrid cube mesh topology (X8 FC + X8 6 port HCM):

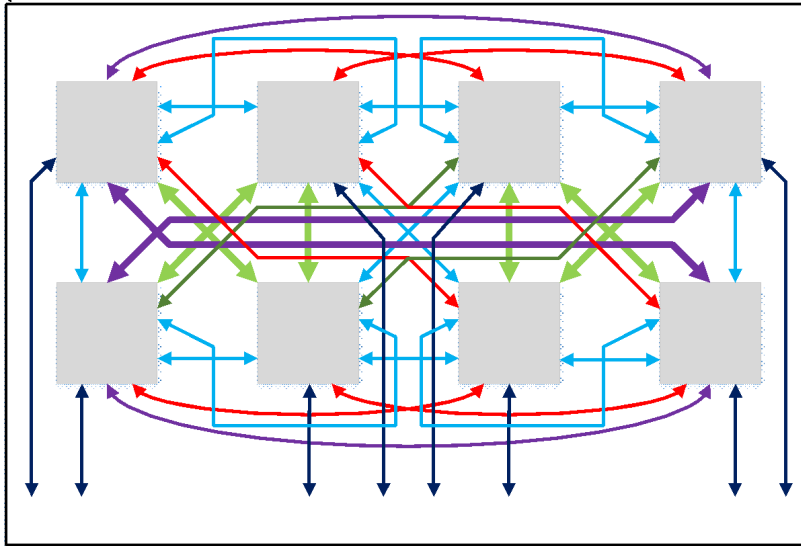


Figure 50 Combined FC/6-Port HCM Topology

Link 1,4,6,7 has a total of 16 lanes, and link 2,3,5 has entire 8 lanes in Figure 50:

- Fully connected: 7 x8 links using port 1-7 first X8(1L-7L)
- 2<sup>nd</sup> half of port 1(1H) can be used for expansion (scale-out)
- 6 port HCM: all 6 ports are in connector 1 only. X16 link for port 4/6, X8 link(5L) for port 5, and 2<sup>nd</sup> half of port 7(7H)

Below figure shows the detailed port mapping and routing guide:

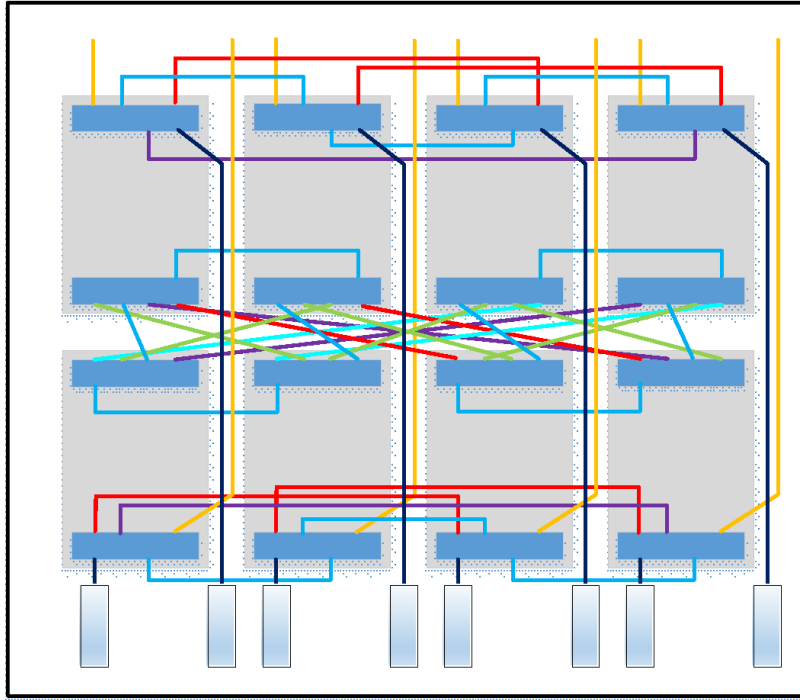


Figure 51 Detail port mapping and routing guidance

Port 4/6(both 4L/6L and 4H/6H), port 5L, 7H are used for 6X8 HCM. It is how embedded to this combined topology:

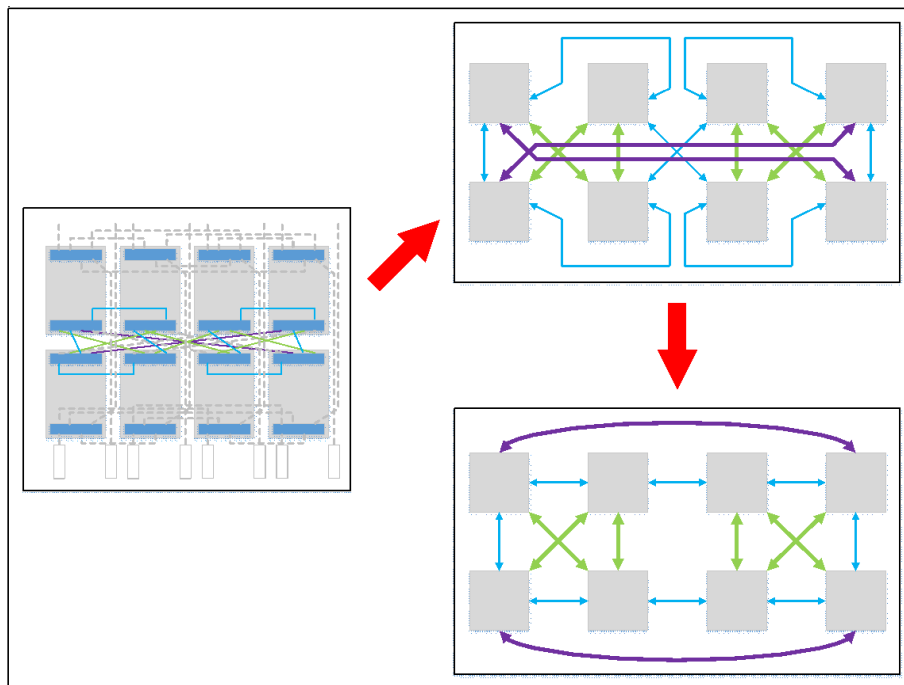


Figure 52 Embedded HCM Topology

### 9.2.6 4D Hypercube

16 modules with 6 links per module the interconnect topology could be a 4d hypercube:

- Four fully connected quads
- Each quad connected to the other 3 quads at all four corners
- The green links below match the green line in the 4d hypercube

As one single PCB cannot fit all 16 modules, these topology interconnects will have a cable or backplane to connect between PCBs. Whether one single PCB holds 4 or 8 modules, the interconnect path may be different. The system integrator may discuss with the module supplier for details. The module defines two QSFPDD ports as the potential scale-up solution.

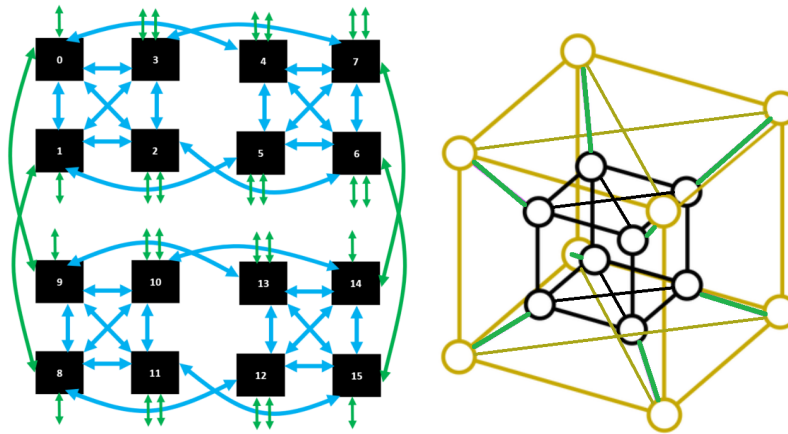


Figure 53 4D Hypercube

### 9.3 LINK\_CONFIG[4:0]

The 5 link configuration strapping bits are pulled up on modules that use them. These bits are strapped to the ground on the baseboard to select logic 0 or left floating to select logic 1. Some OAMs use these LINK\_CONFIG[4:0] strapping bits to determine the interconnect topology for the links between modules and determine the protocol of the “P” Link.

Encodings not listed in the table below are currently un-defined.

Table 7 LINK\_CONFIG[4:0] Encoding Definitions

LINK_CONFIG[4:0]	Definition
00000	Reserved for OAM. Test use by OAM Vendor.
xxxx0 (except for 00000)	Indicates the “P” link is PCIe
01000	6 link HCM, 4 link HCM, and two 3 link fully connected quads as connected in Figure 41.
00110	7 x16 fully connected
01010	6 x 16 link Chordal Ring (Almost Fully Connected) as connected in Figure 44.

01011	6 x 16 link Chordal Ring (Almost Fully Connected) using alternate host interface protocol as connected in Figure 44.
01100	8 link HCM as in Figure 45.
xxxx1 (except for 11111)	Indicates the “P” link is an alternate protocol other than PCIe.
10000	Combined FC/6-Port HCM as in Figure 49.
11111	Indicates an alternate means for identifying the link interconnect topology and configuration is used.

### 9.4 OAM Interconnect PCB Topology

It is recommended to keep the stub for interconnecting links less than 10mils. System integrators should carefully work with module suppliers to plan the PCB routing and address the signal integrity concern.

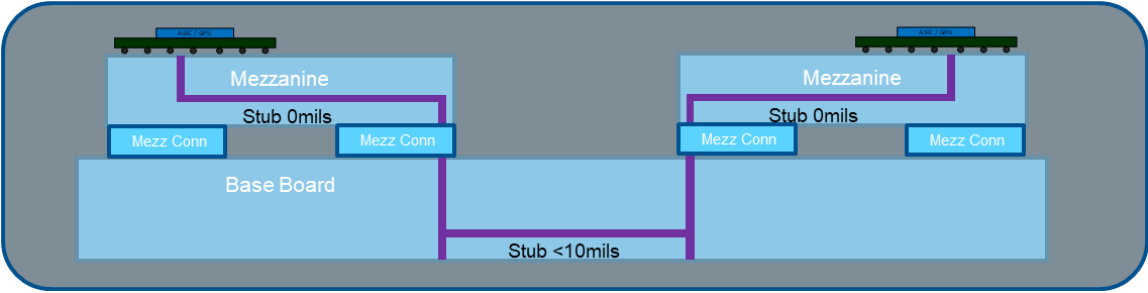


Figure 54 OAM Interconnect PCB Topology

## 10 OAM reference system design

This section gives a system design concept as a reference. Figure 55 Reference System Design shows 8 OAM modules. The plastic top provides a 0.5mm bumper on each side of the 102mm width OAM, and the 1mm gap between each module assembly provides rough alignment, guidance, and Keying as described in Section 6.6. An air baffle is designed into the 33.8mm space to prevent air bypass in the system. Note that the front and rear rows are oriented 180 degrees opposite, as indicated in Section 9. Recommended Alignment Features

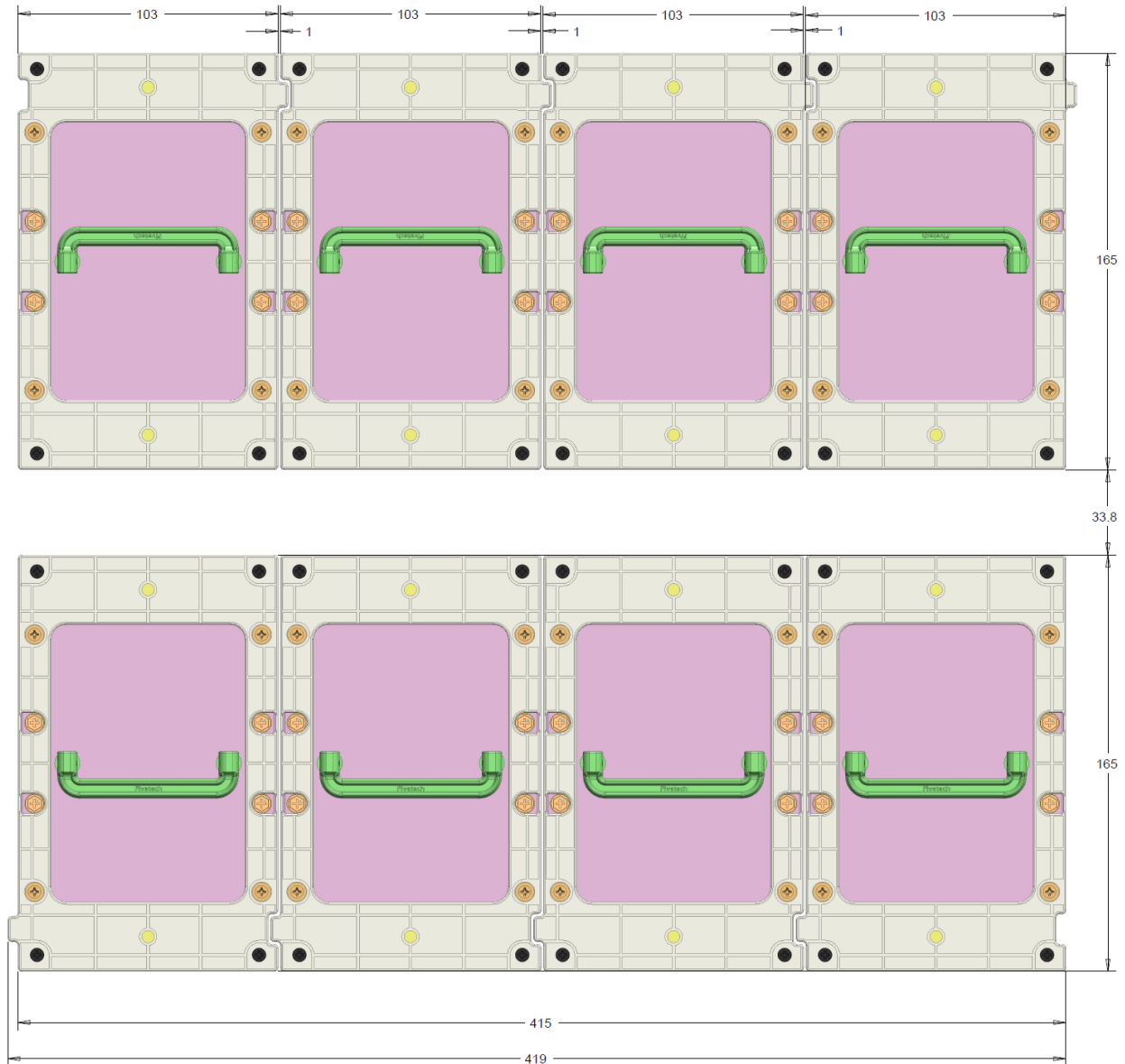


Figure 55 Reference System Design





## 11 OAM Management and Security Requirements

This section describes a common set of management and security requirements for OAM.

### 11.1 Management Interface

The OAM sideband management interface is used by a Management Controller (MC) or Baseboard Management Controller (BMC) to communicate with the OAM. Table 8 below summarizes the sideband management interfaces.

Table 8 Sideband Management Interface

Requirement	Voltage Level	Required
I2C/SMBus 2.0 compliant physical interface(Master/Slave)*	3.3V	Yes
JTAG physical interface(primary)	$V_{ref}$	Yes
I2C/SMBus 2.0 compliant physical interface(Master)	$V_{ref}$	Optional**
JTAG physical interface(secondary)	3.3V	Optional

Note:

\*When MCTP over SMBus is used, the BMC shall support both master and slave modes.

\*\*The master I2C/SMBus physical interface is required for scale-out, baseboard FRU access.

The OAM communicates with the Baseboard Management Controller (BMC) by using:

- SMBus:
  - SMBus supporting 1MHz mode is preferred
  - Standard Intelligence Platform Management Bus (IPMB) and Intelligent Platform Management Interface (IPMI) commands.
  - SMBus ARP protocol
  - Management Component Transport Protocol (MCTP) over SMBus binding ([DMTF DSP0237](#))
- UART (optional)
  - Shall support 115200 Baud Rate
  - For serial console access
- JTAG
  - For register dump, memory dump, debug access
- PCIe (optional)
  - To support MCTP over PCIe binding

### 11.2 Sensor Reporting

An OAM module may have several silicon components, including one or more ASICs implementing acceleration functions. It is crucial that connected sensors of these components (voltage, current/power, temperature, etc.) can be retrieved over sideband interfaces for system management.

The sensor reporting interface will only be accessible in the main power mode (S0). Table 9 Sensor List

Sensor List	Remark
Power/Current (Mem, core, module-level)	
Voltage (core,mem)	
ASIC Temp (hot spot and edge temp)	
ASIC T <sub>jmax</sub>	
Mem Temp for each stack	
Core Power VR Temp	
Core Power VR Vol	
Inlet sensor	Need to define the common location
Outlet sensor	
Power State: <ul style="list-style-type: none"> <li>● Max power mode</li> <li>● Reduced/Capped power mode*</li> </ul>	

\*Note: OAM enters reduced/capped power mode when OAM max power is capped.

Summarizes the sensors reporting list: The report from these sensors improves the system monitoring/management and allows the baseboard management device to access the critical components on the module. It is recommended that the voltage/current/power sensor reporting accuracy is within  $\pm 2\%$ , and the temperature reporting accuracy is within  $\pm 3^{\circ}\text{C}$ .

OAM Module shall support Sensor discovery via IPMI or Platform Level Data Model (PLDM) for Platform Monitoring and Control ([DMTF DSP0248](#)). MC will follow mechanisms specified in DSP0248 to discover sensors supported by the OAM module and their threshold.

Table 9 Sensor List

Sensor List	Remark
Power/Current (Mem, core, module-level)	
Voltage (core,mem)	
ASIC Temp (hot spot and edge temp)	
ASIC T <sub>jmax</sub>	
Mem Temp for each stack	
Core Power VR Temp	
Core Power VR Vol	
Inlet sensor	Need to define the common location
Outlet sensor	
Power State: <ul style="list-style-type: none"> <li>● Max power mode</li> <li>● Reduced/Capped power mode*</li> </ul>	

\*Note: OAM enters reduced/capped power mode when OAM max power is capped.

### 11.3 Error Monitoring/Reporting

System Management Controller (MC) or Baseboard Management Controller (BMC) shall be able to monitor and access the OAM(OAM supplier to specify how to access) through PLDM over MCTP as needed to set thresholds, clear status, determine error counts and syndromes (SW driven interrupt or an Alert pin), and identify error sources/Syndromes, etc.

OAM shall support Platform Level Data Model (PLDM) for Platform Monitoring and Control ([DMTF DSP0248](#)) for error reporting, enabling the module to define state sensors and events for health monitoring and reporting.

Table 10 Error state sensors

Sensor List	Remark
Overall OAM health status	It can be vendor-specific
Memory Error event	
Host bus error event	
Device health event	
Interconnect Link events	
Scale-out link Event	for the scale-out bus, if the different buses from the interconnect links
Other custom/Vendor-specific	

### 11.4 Firmware Update

The OAM should support secure boot. Detail requirements, please refer to section 11.8.1.

OAM supplier shall provide an in-band FW update utility to perform the firmware update.

For out-of-band firmware updates, OAM shall support Platform Level Data Model (PLDM) for firmware update over MCTP as specified in [DMTF DSP0267](#).

Update failure and failure types shall be communicated to BMC as specified in DSP0267.

### 11.5 Power Capping

Module supplier should provide the utility for in-band power capping.

### 11.6 FRU Information

System Management Controller (MC) or Baseboard Management Controller (BMC) shall access related internal registers to get module information (see Table 10).

FRU shall be accessed through Platform Level Data Model (PLDM) for FRU Data, following [DMTF DSP0257](#).

Table 11 FRU Information

FRU Info	Remark
Manufacturing Date	
Manufacturer	
Product Name	
Serial	
Part Number	
FRU ID	
Version	
Asset Tag	
Firmware Version	
OAM Spec Version	
Input Power Mode	High = 48V/54V; Low = 12V
OAM TDP	
SerDes Link Speed	
Custom Data 1	
Custom Data 2	
Custom Data 3	
Custom Data 4	
Custom Data 5	
Custom Data 6	

## 11.7 IO Calibration

The system shall be able to get DDR/PCIe/interconnect training status and margin information. For in-band access, specific tools and/or API shall be provided by the OAM supplier.

## 11.8 OAM Security Requirements

### 11.8.1 Secure Boot

The device must support a secure boot. There are multiple requirements to implement secure boot. Here is a brief list:

- Hardware-based Root of Trust:
  - Immutable Root-of-Trust (e.g., OTP) required for provisioning asymmetric RoT key and other security-related critical information
  - ROM code for minimum support needed for Secure Boot
- Boot Time Verification:
  - On every boot, the ROM code should cryptographically verify mutable firmware code using the asymmetric RoT public key

- All mutable code should be verified by signature authentication before allowing it to execute
- ROM code patching is not permitted in a production device
- In case of failures, please refer to the 'Recovery' section for more details
- TOCTOU Attack Protection:
  - The attacker should not be able to modify the firmware image (Time Of Use) after the signature of the firmware is verified (Time Of Check) during the boot process
- Anti-Rollback Protection:
  - The device must support Security Version Number (SVN) in the immutable memory to protect against downgrade attacks
- Key Revocation or Change of Ownership:
  - The device must support Secure revocation of Intermediate key (used for signing of firmware) in case of the Key compromise
  - For a change of ownership, the device should either support revoking the ownership key or rotating the ownership certificate (as suggested in DSP0274)
- Secure Firmware Update:
  - Signature generation for firmware payload using asymmetric RoT private key is necessary for secure boot
  - The device should be able to authenticate the signed FW payloads before booting up using the payload

For further details on implementation and a detailed set of requirements, please refer to the [OCP Hardware Secure Boot document](#) for more information.

### 11.8.2 Recovery

OAM must support a recovery mechanism to restore the mutable firmware code to a state of integrity if any such firmware code or critical data are detected to have been corrupted or forced to recover through an authorized mechanism.

- OAM should also support two mutable firmware (active and recovery) regions where the recovery firmware is the previously known good image
- In case of failure of redundant copies, OAM should support recovery over the sideband interface.
  - OAM shall support Platform Level Data Model (PLDM) firmware update over MCTP as specified in [DMTF DSP0267](#).
  - Update failure and failure types shall be communicated to BMC as specified in DSP0267
  - Firmware updated out-of-band should still follow the boot-time verification process of secure boot

For further details on implementation and a detailed set of requirements, please refer to the [OCP Recovery document](#) for more information.

### **11.8.3 Debug Capabilities**

Any intrusive debug capabilities (read/write memory, general-purpose register contents, alter control flow), e.g., JTAG, UART, must be disabled for remote access. If needed, they should only be re-enabled via physical access or using cryptographically authorized tokens.

### **11.8.4 Attestation**

It is critical to verify the firmware running on the device dynamically and the device itself cryptographically; this helps establish trust between the devices. It is recommended to support device attestation for OAM.

Here is a short list of generic requirements to support the attestation for OAM:

- Keys, seeds, and device identifiers
- Provisioning Facility (Initial Provisioning Environment Operations and Equipment)
- Device Ownership Provisioning
- Authentication, Attestation, and Enrollment protocol
- Measurement collection and storage

For further details on implementation and a detailed set of requirements, please refer to the [OCP Attestation for System Components v1.0](#) for more information.

## **12 Environmental**

### **12.1 Environmental Requirements**

The OAM shall meet the following environmental requirements:

- Gaseous Contamination: Severity Level G1 per ANSI/ISA 71.04-1985
- Ambient operating temperature range: 5°C to +35°C
- Operating and Storage relative humidity: 20% to 90% (non-condensing)
- Storage temperature range: -20°C to +70°C
- Transportation temperature range: -55°C to +85°C (short-term storage)
- Operating altitude with no de-ratings: 3048m (10000 feet) – recommended as this is a Facebook spec and standard for Telco operation

### **12.2 Regulation**

The vendor needs to provide CB reports of the OAM, which are required to have rack-level CE. The OAM should be compliant with RoHS and WEEE. The PCB should have a UL 94V-0 certificate.



## 13 Revision History

Author	Description	Revision	Date
Whitney Zhao	Initial Release	0.1	6/29/2018
Whitney Zhao	Add pin list	0.2	11/09/2018
Tiffany Jin Cheng Chen	Update Mechanical, Thermal, Reliability sections	Internal release	1/24/2019
Whitney Zhao Siamak Tavallaei	Add power profiles, power sequence requirement Update license information, overview	Internal release	2/4/2019
Tiffany Jin Whitney Zhao	Update module drawings Update pin list and recommended topologies	0.8	2/7/2019
Whitney Zhao	Updated some typos, interconnected topologies Add LINK_CONFIG table	0.82	
Tiffany Jin	Update ME section	0.83	
Cheng Chen	Add liquid cooling concept drawing	0.84	
Whitney Zhao	Update license information. Update topology port mapping Add 156.25Mhz clock for Serdes	0.85	
Whitney Zhao Tiffany Jin Cheng Chen	Update AFC interconnect topology routing recommendation to be compatible with HMC and FC Add management link routing guidance Update SerDes pin map Update ME drawings; more detail on requirements vs. recommendations Add reference data for the increasing need for airflow for OAM cooling as die power increases	0.90	
Whitney Zhao Tiffany Jin	Change SerDes R to 7, update it from X20 to X16 Add two power reduction GPIO pins PWRRDT#[1:0] Add 8-port HCM topology and routing guide Update Vref range to 1.5V-3.3V Update section 8.6, add detailed diagrams on channel loss budget Update OAM_Pin_map to rev1.0: Detail change list pls refer to OAM_Pin_map_rev1.0 spreadsheet Update OAM_Pin_list to R1.0: detail change list pls refer to OAM_Pin_list_Rev1.0 spreadsheet Additional details on force/pin data for Mirror Mezz	1.0	7/25/2019

	Add combined FC/HCM topology port mapping and routing guide. More clarification on dimensions, requirements vs. recommendations Add interconnect scale-out options		
Song Kok Hang	Replace “motherboard?” with “baseboard”. Replace “Accelerator Module” and “Mezzanine Module” with OAM Add IO Type in Table 4 Add note on System power sequencing Update Figure 38, 39, 40, 41, 42, 44, 45, 46, 47, 48, 49, 50, 51 Update Combined FC/6-Port HCM Topology SerDes port mapping Update Table 7 with 6x16-link Chordal Ring and Combined FC/6-Port HCM Topology Add Table 10 for FRU Information Add “silicon die to mated connector” on OAM insertion loss budget Add LINK_CONFIG[4:0] = 01011	1.1	04/03/2020
Hao	Add more details in IO table 4 at section 8.3 Add IO level table after table 4 Define DEBUG_PORT_PRSNT# to 3.3V signal	1.1	4/20/2020
Song Kok Hang	Add OAM Power off Sequence diagram	1.1	5/4/2020
Ben Wei Jubin Mehta Yuval Itkin Whitney Zhao	Modify Chapter 11 and update OAM management and security requirements.	1.1	6/30/2020
Song Kok Hang	Update OAM Power off Sequence diagram to support graceful power down Update Mirror Mezz with Mirror Mezz Pro Add support SerDes speed @112G-PAM4	1.5	10/18/2021